## Demystifying the border of depth-3 circuits

Accepted to the $62^{\text {nd }}$ IEEE Symposium on Foundations of Computer Science (FOCS 2021).
Pranjal Dutta (CMI \& IIT Kanpur) \& Prateek Dwivedi (IIT Kanpur) \& Nitin Saxena (IIT Kanpur).

$$
24^{\text {th }} \text { January, } 2022
$$

School and Conference on Geometric Complexity Theory Jan 2022, Chennai (virtual)

## Table of Contents

1. Algebraic Complexity Theory
2. Border Complexity and GCT
3. Border depth- 3 circuits
4. Derandomizing border depth-3 circuits
5. Conclusion

## Algebraic Complexity Theory

## Basic goal

$\square P$ versus NP. Proving $P \neq N P$ is one of the most fundamental open problems at the intersection of theoretical computer science and mathematics.

## Basic goal

$\square P$ versus NP. Proving $P \neq N P$ is one of the most fundamental open problems at the intersection of theoretical computer science and mathematics.

- Very few techniques are known that could potentially break the 1994 Razborov-Rudich 'natural proofs barrier'.


## Basic goal

$\square P$ versus NP. Proving $P \neq N P$ is one of the most fundamental open problems at the intersection of theoretical computer science and mathematics.

- Very few techniques are known that could potentially break the 1994 Razborov-Rudich 'natural proofs barrier'.

In 2001 Mulmuley and Sohoni published Geometric Complexity Theory 1 (GCT1) in which they describe a method that could potentially break the barrier.

## Basic goal

$\square P$ versus NP. Proving $P \neq N P$ is one of the most fundamental open problems at the intersection of theoretical computer science and mathematics.

- Very few techniques are known that could potentially break the 1994 Razborov-Rudich 'natural proofs barrier'.

In 2001 Mulmuley and Sohoni published Geometric Complexity Theory 1 (GCT1) in which they describe a method that could potentially break the barrier.
$>$ It is built on Valiant's algebraic complexity theory framework (1979) to prove the algebraic $P \neq N P$, namely $V P \neq V N P$.

## Basic goal

$\square P$ versus NP. Proving $P \neq N P$ is one of the most fundamental open problems at the intersection of theoretical computer science and mathematics.

- Very few techniques are known that could potentially break the 1994 Razborov-Rudich 'natural proofs barrier'.

In 2001 Mulmuley and Sohoni published Geometric Complexity Theory 1 (GCT1) in which they describe a method that could potentially break the barrier.
$>$ It is built on Valiant's algebraic complexity theory framework (1979) to prove the algebraic $P \neq N P$, namely $V P \neq V N P$.
$>$ It defines Border Complexity, which was independently defined by Bürgisser (2001).

## Basic goal

$\square P$ versus NP. Proving $P \neq N P$ is one of the most fundamental open problems at the intersection of theoretical computer science and mathematics.

- Very few techniques are known that could potentially break the 1994 Razborov-Rudich 'natural proofs barrier'.

In 2001 Mulmuley and Sohoni published Geometric Complexity Theory 1 (GCT1) in which they describe a method that could potentially break the barrier.
$>$ It is built on Valiant's algebraic complexity theory framework (1979) to prove the algebraic $P \neq N P$, namely $V P \neq V N P$.
$>$ It defines Border Complexity, which was independently defined by Bürgisser (2001). We will consider 'algebraic' notion of border complexity.

## Basic goal

$\square P$ versus NP. Proving $P \neq N P$ is one of the most fundamental open problems at the intersection of theoretical computer science and mathematics.

- Very few techniques are known that could potentially break the 1994 Razborov-Rudich 'natural proofs barrier'.

In 2001 Mulmuley and Sohoni published Geometric Complexity Theory 1 (GCT1) in which they describe a method that could potentially break the barrier.
$>$ It is built on Valiant's algebraic complexity theory framework (1979) to prove the algebraic $P \neq N P$, namely $V P \neq V N P$.
$>$ It defines Border Complexity, which was independently defined by Bürgisser (2001). We will consider 'algebraic' notion of border complexity.
$>$ It proposes to prove border complexity lower bounds using representation theory, which is developed further in [GCT2, Mulmuley-Sohoni'08].

## Basic goal

$\square P$ versus NP. Proving $P \neq N P$ is one of the most fundamental open problems at the intersection of theoretical computer science and mathematics.

- Very few techniques are known that could potentially break the 1994 Razborov-Rudich 'natural proofs barrier'.

In 2001 Mulmuley and Sohoni published Geometric Complexity Theory 1 (GCT1) in which they describe a method that could potentially break the barrier.
$>$ It is built on Valiant's algebraic complexity theory framework (1979) to prove the algebraic $P \neq N P$, namely VP $\neq \mathrm{VNP}$.
$>$ It defines Border Complexity, which was independently defined by Bürgisser (2001). We will consider 'algebraic' notion of border complexity.
$>$ It proposes to prove border complexity lower bounds using representation theory, which is developed further in [GCT2, Mulmuley-Sohoni'08].

- [P $\stackrel{?}{=}$ NP, Aaronson 2011] calls GCT "The String Theory of Computer Science".


## Algebraic circuits



## Algebraic circuits



## Algebraic circuits



## Algebraic circuits



## Algebraic circuits



## Computationally 'easy' polynomials

## Computationally 'easy' polynomials

## $\mathrm{VP}=$ "easy to compute" [Valiant'79]

The class VP is defined as the set of all sequences of polynomials $\left(f_{n}\left(x_{1}, \ldots, x_{n}\right)\right)_{n \geq 1}$ such that $\operatorname{size}\left(f_{n}\right), \operatorname{deg}\left(f_{n}\right)$ are both bounded by $n^{c}$ for some constant $c$.

## Computationally 'easy' polynomials

## $\mathrm{VP}=$ "easy to compute" [Valiant'79]

The class VP is defined as the set of all sequences of polynomials $\left(f_{n}\left(x_{1}, \ldots, x_{n}\right)\right)_{n \geq 1}$ such that $\operatorname{size}\left(f_{n}\right), \operatorname{deg}\left(f_{n}\right)$ are both bounded by $n^{c}$ for some constant $c$.

Examples:
$>f_{n}:=x_{1} \cdots x_{n}$.

## Computationally 'easy' polynomials

## $\mathrm{VP}=$ "easy to compute" [Valiant'79]

The class VP is defined as the set of all sequences of polynomials $\left(f_{n}\left(x_{1}, \ldots, x_{n}\right)\right)_{n \geq 1}$ such that $\operatorname{size}\left(f_{n}\right), \operatorname{deg}\left(f_{n}\right)$ are both bounded by $n^{c}$ for some constant $c$.

Examples:
$>f_{n}:=x_{1} \cdots x_{n}$.
$>f_{n}:=x_{1}^{n}+\ldots+x_{n}^{n}$.

## Computationally 'easy' polynomials

## VP = "easy to compute" [Valiant'79]

The class VP is defined as the set of all sequences of polynomials $\left(f_{n}\left(x_{1}, \ldots, x_{n}\right)\right)_{n \geq 1}$ such that $\operatorname{size}\left(f_{n}\right), \operatorname{deg}\left(f_{n}\right)$ are both bounded by $n^{c}$ for some constant $c$.

Examples:
$>f_{n}:=x_{1} \cdots x_{n}$.
$>f_{n}:=x_{1}^{n}+\ldots+x_{n}^{n}$.
$>f_{n}:=\sum_{S \subseteq[n]} \prod_{j \in S} x_{j}$

## Computationally 'easy' polynomials

## $\mathrm{VP}=$ "easy to compute" [Valiant'79]

The class VP is defined as the set of all sequences of polynomials $\left(f_{n}\left(x_{1}, \ldots, x_{n}\right)\right)_{n \geq 1}$ such that $\operatorname{size}\left(f_{n}\right), \operatorname{deg}\left(f_{n}\right)$ are both bounded by $n^{c}$ for some constant $c$.

Examples:
$>f_{n}:=x_{1} \cdots x_{n}$.
$>f_{n}:=x_{1}^{n}+\ldots+x_{n}^{n}$.
$>f_{n}:=\sum_{S \subseteq[n]} \prod_{j \in S} x_{j}=\prod_{i=1}^{n}\left(1+x_{i}\right)$.

## The determinant polynomial

## The determinant polynomial

$\square$ Let $X_{n}=\left[x_{i, j}\right]_{1 \leq i, j \leq n}$ be a $n \times n$ matrix of distinct variables $x_{i, j}$. Let $S_{n}:=\{\pi \mid \pi:\{1, \ldots, n\} \longrightarrow\{1, \ldots, n\}$ such that $\pi$ is bijective $\}$. Define

$$
f_{n}:=\operatorname{det}\left(X_{n}\right)=\sum_{\pi \in S_{n}} \operatorname{sgn}(\pi) \prod_{i=1}^{n} x_{i, \pi(i)}
$$

## The determinant polynomial

$\square$ Let $X_{n}=\left[x_{i, j}\right]_{1 \leq i, j \leq n}$ be a $n \times n$ matrix of distinct variables $x_{i, j}$. Let $S_{n}:=\{\pi \mid \pi:\{1, \ldots, n\} \longrightarrow\{1, \ldots, n\}$ such that $\pi$ is bijective $\}$. Define

$$
f_{n}:=\operatorname{det}\left(X_{n}\right)=\sum_{\pi \in S_{n}} \operatorname{sgn}(\pi) \prod_{i=1}^{n} x_{i, \pi(i)}
$$

$\square$ det is universal, i.e. any polynomial $f(\boldsymbol{x})$ can be computed as a determinant of a square matrix whose entries are polynomials of degree $\leq 1$.

## The determinant polynomial

$\square$ Let $X_{n}=\left[x_{i, j}\right]_{1 \leq i, j \leq n}$ be a $n \times n$ matrix of distinct variables $x_{i, j}$. Let $S_{n}:=\{\pi \mid \pi:\{1, \ldots, n\} \longrightarrow\{1, \ldots, n\}$ such that $\pi$ is bijective $\}$. Define

$$
f_{n}:=\operatorname{det}\left(X_{n}\right)=\sum_{\pi \in S_{n}} \operatorname{sgn}(\pi) \prod_{i=1}^{n} x_{i, \pi(i)}
$$

$\square$ det is universal, i.e. any polynomial $f(\boldsymbol{x})$ can be computed as a determinant of a square matrix whose entries are polynomials of degree $\leq 1$.

The minimum dimension of the matrix to compute $f$, is called the determinantal complexity $\mathrm{dc}(f)$.

## The determinant polynomial

$\square$ Let $X_{n}=\left[x_{i, j}\right]_{1 \leq i, j \leq n}$ be a $n \times n$ matrix of distinct variables $x_{i, j}$. Let $S_{n}:=\{\pi \mid \pi:\{1, \ldots, n\} \longrightarrow\{1, \ldots, n\}$ such that $\pi$ is bijective $\}$. Define

$$
f_{n}:=\operatorname{det}\left(X_{n}\right)=\sum_{\pi \in S_{n}} \operatorname{sgn}(\pi) \prod_{i=1}^{n} x_{i, \pi(i)}
$$

det is universal, i.e. any polynomial $f(\boldsymbol{x})$ can be computed as a determinant of a square matrix whose entries are polynomials of degree $\leq 1$.

The minimum dimension of the matrix to compute $f$, is called the determinantal complexity $\mathrm{dc}(f)$.
E.g. $\operatorname{dc}\left(x_{1} \cdots x_{n}\right)=n$, since

$$
x_{1} \cdots x_{n}=\operatorname{det}\left(\begin{array}{cccc}
x_{1} & 0 & \ldots & 0 \\
0 & x_{2} & \ldots & 0 \\
\vdots & \vdots & \vdots & \vdots \\
0 & 0 & \ldots & x_{n}
\end{array}\right)
$$

## Another 'easy' class VBP

V VBP: The class VBP is defined as the set of all sequences of polynomials $\left(f_{n}\right)_{n}$ with polynomially bounded $\mathrm{dc}\left(f_{n}\right)$.

## Another 'easy' class VBP

VBP: The class VBP is defined as the set of all sequences of polynomials $\left(f_{n}\right)_{n}$ with polynomially bounded $\mathrm{dc}\left(f_{n}\right)$.
$\square \mathrm{VBP} \subseteq \mathrm{VP}$. It is open whether VBP $\stackrel{?}{=} \mathrm{VP}$.

## Another 'easy' class VBP

V VBP: The class VBP is defined as the set of all sequences of polynomials $\left(f_{n}\right)_{n}$ with polynomially bounded $\mathrm{dc}\left(f_{n}\right)$.
$\square \mathrm{VBP} \subseteq \mathrm{VP}$. It is open whether VBP $\stackrel{?}{=} \mathrm{VP}$.
Often we will say $f$ has a small ABP. This just means $\operatorname{dc}(f)$ is small.

## Another 'easy' class VBP

V VBP: The class VBP is defined as the set of all sequences of polynomials $\left(f_{n}\right)_{n}$ with polynomially bounded $\mathrm{dc}\left(f_{n}\right)$.
$\square \mathrm{VBP} \subseteq \mathrm{VP}$. It is open whether VBP $\stackrel{?}{=} \mathrm{VP}$.
Often we will say $f$ has a small ABP. This just means $\operatorname{dc}(f)$ is small.
Connections: Linear algebra, Volume, counting planar matchings.

## ‘Hard' polynomials?

$\square$ Are there hard polynomial families $\left(f_{n}\right)_{n}$ such that it cannot be computed by an $n^{C}$-size circuit, for every constant $c$ ? i.e. $\operatorname{size}\left(f_{n}\right)=n^{\omega(1)}$ ?

## ‘Hard' polynomials?

$\square$ Are there hard polynomial families $\left(f_{n}\right)_{n}$ such that it cannot be computed by an $n^{C}$-size circuit, for every constant $c$ ? i.e. $\operatorname{size}\left(f_{n}\right)=n^{\omega(1)}$ ?
$\square$ A random polynomial with 0-1 coefficient is hard [Hrubeš-Yehudayoff ToC'11].

## ‘Hard' polynomials?

$\square$ Are there hard polynomial families $\left(f_{n}\right)_{n}$ such that it cannot be computed by an $n^{C}$-size circuit, for every constant $c$ ? i.e. $\operatorname{size}\left(f_{n}\right)=n^{\omega(1)}$ ?
$\square$ A random polynomial with 0-1 coefficient is hard [Hrubeš-Yehudayoff ToC'11]. Challenge: Find an explicit one!

## 'Hard' polynomials?

$\square$ Are there hard polynomial families $\left(f_{n}\right)_{n}$ such that it cannot be computed by an $n^{c}$-size circuit, for every constant $c$ ? i.e. size $\left(f_{n}\right)=n^{\omega(1)}$ ?
$\square$ A random polynomial with 0-1 coefficient is hard [Hrubeš-Yehudayoff ToC'11]. Challenge: Find an explicit one!

- Candidate hard polynomial:

$$
\operatorname{perm}\left(X_{n}\right)=\sum_{\pi \in S_{n}} \prod_{i=1}^{n} x_{i, \pi(i)}
$$

## 'Hard' polynomials?

$\square$ Are there hard polynomial families $\left(f_{n}\right)_{n}$ such that it cannot be computed by an $n^{c}$-size circuit, for every constant $c$ ? i.e. size $\left(f_{n}\right)=n^{\omega(1)}$ ?
$\square$ A random polynomial with 0-1 coefficient is hard [Hrubeš-Yehudayoff ToC'11]. Challenge: Find an explicit one!

- Candidate hard polynomial:

$$
\operatorname{perm}\left(X_{n}\right)=\sum_{\pi \in S_{n}} \prod_{i=1}^{n} x_{i, \pi(i)}
$$

$\square$ perm is universal, i.e. any polynomial $f(\boldsymbol{x})$ can be computed as a permanent of a square matrix whose entries are polynomials of degree $\leq 1$.

## ‘Hard' polynomials?

$\square$ Are there hard polynomial families $\left(f_{n}\right)_{n}$ such that it cannot be computed by an $n^{c}$-size circuit, for every constant $c$ ? i.e. size $\left(f_{n}\right)=n^{\omega(1)}$ ?

A A random polynomial with 0-1 coefficient is hard [Hrubeš-Yehudayoff ToC' 11 ]. Challenge: Find an explicit one!

- Candidate hard polynomial:

$$
\operatorname{perm}\left(X_{n}\right)=\sum_{\pi \in S_{n}} \prod_{i=1}^{n} x_{i, \pi(i)}
$$

$\square$ perm is universal, i.e. any polynomial $f(\boldsymbol{x})$ can be computed as a permanent of a square matrix whose entries are polynomials of degree $\leq 1$.

- The minimum dimension of the matrix to compute $f$, is called the permanental complexity $\mathrm{pc}(f)$.


## Valiant's Conjecture

## VNP = "hard to compute?" [Valiant 1979]

The class VNP is defined as the set of all sequences of polynomials $\left(f_{n}\left(x_{1}, \ldots, x_{n}\right)\right)_{n \geq 1}$ such that $\mathrm{pc}\left(f_{n}\right)$ is bounded by $n^{c}$ for some constant $c$.

## Valiant's Conjecture

## VNP = "hard to compute?" [Valiant 1979]

The class VNP is defined as the set of all sequences of polynomials $\left(f_{n}\left(x_{1}, \ldots, x_{n}\right)\right)_{n \geq 1}$ such that $\mathrm{pc}\left(f_{n}\right)$ is bounded by $n^{c}$ for some constant $c$.

Connections: Enumeration, counting matchings, Bosons etc.

## Valiant's Conjecture

## VNP = "hard to compute?" [Valiant 1979]

The class VNP is defined as the set of all sequences of polynomials $\left(f_{n}\left(x_{1}, \ldots, x_{n}\right)\right)_{n \geq 1}$ such that $\mathrm{pc}\left(f_{n}\right)$ is bounded by $n^{c}$ for some constant $c$.

Connections: Enumeration, counting matchings, Bosons etc.
$\square \mathrm{VBP} \subseteq \mathrm{VP} \subseteq \mathrm{VNP}$.

## Valiant's Conjecture

## VNP = "hard to compute?" [Valiant 1979]

The class VNP is defined as the set of all sequences of polynomials $\left(f_{n}\left(x_{1}, \ldots, x_{n}\right)\right)_{n \geq 1}$ such that $\mathrm{pc}\left(f_{n}\right)$ is bounded by $n^{c}$ for some constant $c$.

Connections: Enumeration, counting matchings, Bosons etc.

- $\mathrm{VBP} \subseteq \mathrm{VP} \subseteq \mathrm{VNP}$.


## Valiant's Conjecture [Valiant 1979]

VBP $\neq \mathrm{VNP} \& \mathrm{VP} \neq \mathrm{VNP}$. Equivalently, dc $\left(\right.$ perm $\left._{n}\right)$ and size $\left(\right.$ perm $\left._{n}\right)$ are both $n^{\omega(1)}$.
[Also, VBP $\neq \mathrm{VP}$. A candidate?]

## Connections to Boolean circuit complexity

## Connections to Boolean circuit complexity

Separating algebraic classes are "easier" than separating classes in Boolean complexity [Bürgisser 1998]:

## Connections to Boolean circuit complexity

Separating algebraic classes are "easier" than separating classes in Boolean complexity [Bürgisser 1998]:
$>P /$ poly $\neq N P /$ poly $\Longrightarrow \mathrm{VBP} \neq \mathrm{VNP}$ and $\mathrm{VP} \neq \mathrm{VNP}$ (over finite fields).

## Connections to Boolean circuit complexity

Separating algebraic classes are "easier" than separating classes in Boolean complexity [Bürgisser 1998]:
$>P /$ poly $\neq N P /$ poly $\Longrightarrow \mathrm{VBP} \neq \mathrm{VNP}$ and $\mathrm{VP} \neq \mathrm{VNP}$ (over finite fields).
> Assuming GRH (Generalized Riemann hypothesis), the results hold over $\mathbb{C}$ as well.

## Summary

## Summary

- A recent breakthrough. [Limaye-Srinivasan-Tavenas FOCS 2021] showed the first superpolynomial lower bound for general constant-depth algebraic circuits!


## Summary

- A recent breakthrough. [Limaye-Srinivasan-Tavenas FOCS 2021] showed the first superpolynomial lower bound for general constant-depth algebraic circuits!

Can there be 'algebraic natural proofs' to prove VP $\neq$ VNP? Some answers: [Chatterjee-Kumar-Ramya-Saptharishi-Tengse 2020, Kumar-Ramya-Saptharishi-Tengse 2020].

## Border Complexity and GCT

## Waring rank

## Waring rank

Can 'approximations' also help in algebraic computational models?

## Waring rank

Can 'approximations' also help in algebraic computational models?
$\square$ An important measure is Waring rank, denoted $\mathrm{WR}(\cdot)$.

## Waring rank

Can 'approximations' also help in algebraic computational models?
$\square$ An important measure is Waring rank, denoted WR( $\cdot$ ).

## Waring Rank

The smallest $r$ such that a homogeneous degree $d$ polynomial $h$ can be written as a sum of $d$-th power of linear forms $\ell_{i}$, i.e. $h=\sum_{i=1}^{r} \ell_{i}^{d}$.

## Waring rank

Can 'approximations' also help in algebraic computational models?
$\square$ An important measure is Waring rank, denoted WR(•).

## Waring Rank

The smallest $r$ such that a homogeneous degree $d$ polynomial $h$ can be written as a sum of $d$-th power of linear forms $\ell_{i}$, i.e. $h=\sum_{i=1}^{r} \ell_{i}^{d}$.

Recall: $h=\sum_{e_{1}, \ldots, e_{n}} a_{e_{1}, \ldots, e_{n}} x_{1}^{e_{1}} \cdots x_{n}^{e_{n}}$, is called homogeneous degree $d$ polynomial if $\sum e_{i}=d$, for every tupple $\left(e_{1}, \ldots, e_{n}\right)$ such that $a_{e_{1}, \ldots, e_{n}} \neq 0$.

## Waring rank

Can 'approximations' also help in algebraic computational models?
$\square$ An important measure is Waring rank, denoted WR(•).

## Waring Rank

The smallest $r$ such that a homogeneous degree $d$ polynomial $h$ can be written as a sum of $d$-th power of linear forms $\ell_{i}$, i.e. $h=\sum_{i=1}^{r} \ell_{i}^{d}$.
$\square$ Recall: $h=\sum_{e_{1}, . ., e_{n}} a_{e_{1}, \ldots, e_{n}} x_{1}^{e_{1}} \cdots x_{n}^{e_{n}}$, is called homogeneous degree $d$ polynomial if $\sum e_{i}=d$, for every tupple $\left(e_{1}, \ldots, e_{n}\right)$ such that $a_{e_{1}, \ldots, e_{n}} \neq 0$.

Recall: A linear form $\ell$ is of the form $a_{1} x_{1}+\ldots+a_{n} x_{n}$.

## Waring rank

$\square$ Can 'approximations' also help in algebraic computational models?
$\square$ An important measure is Waring rank, denoted WR(•).

## Waring Rank

The smallest $r$ such that a homogeneous degree $d$ polynomial $h$ can be written as a sum of $d$-th power of linear forms $\ell_{i}$, i.e. $h=\sum_{i=1}^{r} \ell_{i}^{d}$.

Recall: $h=\sum_{e_{1}, \ldots, e_{n}} a_{e_{1}, \ldots, e_{n}} x_{1}^{e_{1}} \cdots x_{n}^{e_{n}}$, is called homogeneous degree $d$ polynomial if $\sum e_{i}=d$, for every tupple $\left(e_{1}, \ldots, e_{n}\right)$ such that $a_{e_{1}, \ldots, e_{n}} \neq 0$.

Recall: A linear form $\ell$ is of the form $a_{1} x_{1}+\ldots+a_{n} x_{n}$.
For any homogeneous polynomial $h, \mathrm{WR}(h)$ is finite.

## Waring rank

Can 'approximations' also help in algebraic computational models?
$\square$ An important measure is Waring rank, denoted WR(•).

## Waring Rank

The smallest $r$ such that a homogeneous degree $d$ polynomial $h$ can be written as a sum of $d$-th power of linear forms $\ell_{i}$, i.e. $h=\sum_{i=1}^{r} \ell_{i}^{d}$.

Recall: $h=\sum_{e_{1}, \ldots, e_{n}} a_{e_{1}, \ldots, e_{n}} x_{1}^{e_{1}} \cdots x_{n}^{e_{n}}$, is called homogeneous degree $d$ polynomial if $\sum e_{i}=d$, for every tupple $\left(e_{1}, \ldots, e_{n}\right)$ such that $a_{e_{1}, \ldots, e_{n}} \neq 0$.

Recall: A linear form $\ell$ is of the form $a_{1} x_{1}+\ldots+a_{n} x_{n}$.
For any homogeneous polynomial $h, \mathrm{WR}(h)$ is finite.

- WR $(h) \leq r$ is denoted as $h \in \Sigma^{[r]} \wedge \Sigma$ (homogeneous depth-3 diagonal circuits).


## Approximation helps!

- Example: $\operatorname{WR}\left(x^{2} y\right) \leq 3$, because


## Approximation helps!

Example: $\operatorname{WR}\left(x^{2} y\right) \leq 3$, because

$$
x^{2} y=\frac{1}{6} \cdot(x+y)^{3}-\frac{1}{6} \cdot(x-y)^{3}-\frac{1}{3} \cdot y^{3} .
$$

## Approximation helps!

Example: $\mathrm{WR}\left(x^{2} y\right) \leq 3$, because

$$
x^{2} y=\frac{1}{6} \cdot(x+y)^{3}-\frac{1}{6} \cdot(x-y)^{3}-\frac{1}{3} \cdot y^{3} .
$$

- Prove: $\operatorname{WR}\left(x^{2} y\right)=3$.


## Approximation helps!

Example: $\mathrm{WR}\left(x^{2} y\right) \leq 3$, because

$$
x^{2} y=\frac{1}{6} \cdot(x+y)^{3}-\frac{1}{6} \cdot(x-y)^{3}-\frac{1}{3} \cdot y^{3}
$$

- Prove: $\operatorname{WR}\left(x^{2} y\right)=3$.

Let $h_{\epsilon}:=\frac{1}{3 \epsilon}\left((x+\epsilon y)^{3}-x^{3}\right)$

## Approximation helps!

Example: $\mathrm{WR}\left(x^{2} y\right) \leq 3$, because

$$
x^{2} y=\frac{1}{6} \cdot(x+y)^{3}-\frac{1}{6} \cdot(x-y)^{3}-\frac{1}{3} \cdot y^{3}
$$

- Prove: $\operatorname{WR}\left(x^{2} y\right)=3$.
- Let $h_{\epsilon}:=\frac{1}{3 \epsilon}\left((x+\epsilon y)^{3}-x^{3}\right)$

$$
=x^{2} y+\epsilon x y^{2}+\frac{\epsilon^{2}}{3} y^{3} \xrightarrow{\epsilon \rightarrow 0} x^{2} y=: h \quad \text { (coefficient-wise). }
$$

## Approximation helps!

- Example: $\operatorname{WR}\left(x^{2} y\right) \leq 3$, because

$$
x^{2} y=\frac{1}{6} \cdot(x+y)^{3}-\frac{1}{6} \cdot(x-y)^{3}-\frac{1}{3} \cdot y^{3} .
$$

- Prove: $\operatorname{WR}\left(x^{2} y\right)=3$.
- Let $h_{\epsilon}:=\frac{1}{3 \epsilon}\left((x+\epsilon y)^{3}-x^{3}\right)$

$$
=x^{2} y+\epsilon x y^{2}+\frac{\epsilon^{2}}{3} y^{3} \xrightarrow{\epsilon \rightarrow 0} x^{2} y=: h \quad \text { (coefficient-wise). }
$$

. Note: $\operatorname{WR}\left(h_{\epsilon}\right) \leq 2$, for any fixed non-zero $\epsilon$. But $\operatorname{WR}(h)=3$ !

## Approximation helps!

- Example: $\operatorname{WR}\left(x^{2} y\right) \leq 3$, because

$$
x^{2} y=\frac{1}{6} \cdot(x+y)^{3}-\frac{1}{6} \cdot(x-y)^{3}-\frac{1}{3} \cdot y^{3} .
$$

- Prove: $\operatorname{WR}\left(x^{2} y\right)=3$.
- Let $h_{\epsilon}:=\frac{1}{3 \epsilon}\left((x+\epsilon y)^{3}-x^{3}\right)$

$$
=x^{2} y+\epsilon x y^{2}+\frac{\epsilon^{2}}{3} y^{3} \xrightarrow{\epsilon \rightarrow 0} x^{2} y=: h \quad \text { (coefficient-wise). }
$$

- Note: $\operatorname{WR}\left(h_{\epsilon}\right) \leq 2$, for any fixed non-zero $\epsilon$. But $\mathrm{WR}(h)=3$ !



## So, Border Waring rank

## So, Border Waring rank

## Border Waring rank

The border Waring rank $\overline{\mathrm{WR}}(h)$ is defined as the smallest $n$ such that $h$ can be approximated arbitrarily closely by polynomials of Waring rank $\leq n$.

## So, Border Waring rank

## Border Waring rank

The border Waring rank $\overline{\mathrm{WR}}(h)$ is defined as the smallest $n$ such that $h$ can be approximated arbitrarily closely by polynomials of Waring rank $\leq n$.

- $\overline{\mathrm{WR}}\left(x^{2} y\right)=2$ but $\mathrm{WR}\left(x^{2} y\right)=3$.


## So, Border Waring rank

## Border Waring rank

The border Waring rank $\overline{\mathrm{WR}}(h)$ is defined as the smallest $n$ such that $h$ can be approximated arbitrarily closely by polynomials of Waring rank $\leq n$.

- $\overline{\mathrm{WR}}\left(x^{2} y\right)=2$ but $\mathrm{WR}\left(x^{2} y\right)=3$.
$\square$ The subtlety is gone: $X_{n}:=\{h \mid \mathrm{WR}(h) \leq n\}$, is now a closed set.


## So, Border Waring rank

## Border Waring rank

The border Waring rank $\overline{\mathrm{WR}}(h)$ is defined as the smallest $n$ such that $h$ can be approximated arbitrarily closely by polynomials of Waring rank $\leq n$.
$\square \overline{\mathrm{WR}}\left(x^{2} y\right)=2$ but $\mathrm{WR}\left(x^{2} y\right)=3$.
$\square$ The subtlety is gone: $X_{n}:=\{h \mid \overline{\mathrm{WR}}(h) \leq n\}$, is now a closed set.
On to proving lower bounds: To show $\overline{\mathrm{WR}}(p)>n$, for some $p$, it suffices to show that $p \notin X_{n}$, i.e. find a continuous function $f$ that vanishes on $X_{n}$ but not on $p$.

## Border complexity

Replace Waring rank by any sensible measure $\Gamma$. It can be size, $\mathrm{dc}, \mathrm{pc}$ and so on.

## Border complexity

$\square$ Replace Waring rank by any sensible measure $\Gamma$. It can be size, dc, $p c$ and so on.

- For any $\Gamma$, we can define the border complexity measure $\bar{\Gamma}$ via: $\bar{\Gamma}(h)$ is the smallest $n$ such that $h(\boldsymbol{x})$ can be approximated arbitrarily closely by polynomials $h_{\epsilon}(\boldsymbol{x})$ with $\Gamma\left(h_{\epsilon}\right) \leq n$.


## Border complexity

$\square$ Replace Waring rank by any sensible measure $\Gamma$. It can be size, dc, $p c$ and so on.

- For any $\Gamma$, we can define the border complexity measure $\bar{\Gamma}$ via:
$\bar{\Gamma}(h)$ is the smallest $n$ such that $h(\boldsymbol{x})$ can be approximated arbitrarily closely by polynomials $h_{\epsilon}(\boldsymbol{x})$ with $\Gamma\left(h_{\epsilon}\right) \leq n$. In other words,

$$
\lim _{\epsilon \rightarrow 0} h_{\epsilon}=h \text { (coefficient-wise) }
$$

## Border complexity

$\square$ Replace Waring rank by any sensible measure $\Gamma$. It can be size, dc, $p c$ and so on.

- For any $\Gamma$, we can define the border complexity measure $\bar{\Gamma}$ via:
$\bar{\Gamma}(h)$ is the smallest $n$ such that $h(\boldsymbol{x})$ can be approximated arbitrarily closely by polynomials $h_{\epsilon}(\boldsymbol{x})$ with $\Gamma\left(h_{\epsilon}\right) \leq n$. In other words,

$$
\lim _{\epsilon \rightarrow 0} h_{\epsilon}=h \text { (coefficient-wise) }
$$

Important border rank: border tensor rank, related to border Waring rank!

## Border complexity

$\square$ Replace Waring rank by any sensible measure $\Gamma$. It can be size, dc, $p c$ and so on.

- For any $\Gamma$, we can define the border complexity measure $\bar{\Gamma}$ via:
$\bar{\Gamma}(h)$ is the smallest $n$ such that $h(\boldsymbol{x})$ can be approximated arbitrarily closely by polynomials $h_{\epsilon}(\boldsymbol{x})$ with $\Gamma\left(h_{\epsilon}\right) \leq n$. In other words,

$$
\lim _{\epsilon \rightarrow 0} h_{\epsilon}=h \text { (coefficient-wise) }
$$

Important border rank: border tensor rank, related to border Waring rank! Border tensor rank is directly related to the matrix multiplication exponent $\omega$ [Bini 1980, Coppersmith-Winograd 1990].

## Approximative circuits

- Coefficients in the earlier definition can be arbitrary depending on the parameter $\epsilon$. Can it be 'nicer'?


## Approximative circuits

Coefficients in the earlier definition can be arbitrary depending on the parameter $\epsilon$. Can it be 'nicer'?

- Yes! Via 'approximative circuits'.


## Approximative circuits (continued)



## Algebraic approximation

## Algebraic approximation

$\square$ Suppose, we assume the following:
$>g(\boldsymbol{x}, \epsilon) \in \mathbb{F}\left[x_{1}, \ldots, x_{n}, \epsilon\right]$, i.e. it is a polynomial of the form

$$
g(\boldsymbol{x}, \epsilon)=\sum_{i=0}^{M} g_{i}\left(x_{1}, \ldots, x_{n}\right) \cdot \epsilon^{i}
$$

## Algebraic approximation

$\square$ Suppose, we assume the following:
$>g(\boldsymbol{x}, \epsilon) \in \mathbb{F}\left[x_{1}, \ldots, x_{n}, \epsilon\right]$, i.e. it is a polynomial of the form

$$
g(\boldsymbol{x}, \epsilon)=\sum_{i=0}^{M} g_{i}\left(x_{1}, \ldots, x_{n}\right) \cdot \epsilon^{i}
$$

$>$ Can we say anything about the complexity of $g_{0}$ ?

## Algebraic approximation

$\square$ Suppose, we assume the following:
$>g(\boldsymbol{x}, \epsilon) \in \mathbb{F}\left[x_{1}, \ldots, x_{n}, \epsilon\right]$, i.e. it is a polynomial of the form

$$
g(\boldsymbol{x}, \epsilon)=\sum_{i=0}^{M} g_{i}\left(x_{1}, \ldots, x_{n}\right) \cdot \epsilon^{i}
$$

$>$ Can we say anything about the complexity of $g_{0}$ ?

- Obvious attempt:
$>$ Since, $g(\boldsymbol{x}, 0)=g_{0}$, why not just set $\epsilon=0$ ?!


## Algebraic approximation

$\square$ Suppose, we assume the following:
$>g(\boldsymbol{x}, \epsilon) \in \mathbb{F}\left[x_{1}, \ldots, x_{n}, \epsilon\right]$, i.e. it is a polynomial of the form

$$
g(\boldsymbol{x}, \epsilon)=\sum_{i=0}^{M} g_{i}\left(x_{1}, \ldots, x_{n}\right) \cdot \epsilon^{i}
$$

$>$ Can we say anything about the complexity of $g_{0}$ ?

- Obvious attempt:
$>$ Since, $g(\boldsymbol{x}, 0)=g_{0}$, why not just set $\epsilon=0$ ?! Setting $\epsilon=0$ may not be 'legal' as it could be using $1 / \epsilon$ in the wire. Though it is well-defined!


## Algebraic approximation

$\square$ Suppose, we assume the following:
$>g(\boldsymbol{x}, \epsilon) \in \mathbb{F}\left[x_{1}, \ldots, x_{n}, \epsilon\right]$, i.e. it is a polynomial of the form

$$
g(\boldsymbol{x}, \epsilon)=\sum_{i=0}^{M} g_{i}\left(x_{1}, \ldots, x_{n}\right) \cdot \epsilon^{i}
$$

$>$ Can we say anything about the complexity of $g_{0}$ ?

- Obvious attempt:
$>$ Since, $g(\boldsymbol{x}, 0)=g_{0}$, why not just set $\epsilon=0$ ?! Setting $\epsilon=0$ may not be 'legal' as it could be using $1 / \epsilon$ in the wire. Though it is well-defined!

Summary: $g_{0}$ is really something non-trivial and being 'approximated' by the circuit since $\lim _{\epsilon \rightarrow 0} g(\boldsymbol{x}, \epsilon)=g_{0}$.

## Algebraic approximation (continued)

## Algebraic approximation (continued)

## Algebraic Approximation [Bürgisser 2004]

A polynomial $h(x) \in \mathbb{F}[\boldsymbol{x}]$ has approximative complexity $s$, if there is a circuit $g(\boldsymbol{x}, \epsilon) \in \mathbb{F}(\epsilon)[\boldsymbol{x}]$, of size $S$, over $\mathbb{F}(\epsilon)$, and a polynomial $S(\boldsymbol{x}, \epsilon) \in \mathbb{F}[\epsilon][\boldsymbol{x}]$ such that $g(\boldsymbol{x}, \epsilon)=h(\boldsymbol{x})+\epsilon \cdot S(\boldsymbol{x}, \epsilon)$. In other words, $\lim _{\epsilon \rightarrow 0} g=h$.

## Algebraic approximation (continued)

## Algebraic Approximation [Bürgisser 2004]

A polynomial $h(x) \in \mathbb{F}[\boldsymbol{x}]$ has approximative complexity $s$, if there is a circuit $g(\boldsymbol{x}, \epsilon) \in \mathbb{F}(\epsilon)[\boldsymbol{x}]$, of size $S$, over $\mathbb{F}(\epsilon)$, and a polynomial $S(\boldsymbol{x}, \epsilon) \in \mathbb{F}[\epsilon][\boldsymbol{x}]$ such that $g(\boldsymbol{x}, \epsilon)=h(\boldsymbol{x})+\epsilon \cdot S(\boldsymbol{x}, \epsilon)$. In other words, $\lim _{\epsilon \rightarrow 0} g=h$.

- $\overline{\operatorname{size}}(h) \leq \operatorname{size}(h)$.


## Algebraic approximation (continued)

## Algebraic Approximation [Bürgisser 2004]

A polynomial $h(x) \in \mathbb{F}[\boldsymbol{x}]$ has approximative complexity $s$, if there is a circuit $g(\boldsymbol{x}, \epsilon) \in \mathbb{F}(\epsilon)[\boldsymbol{x}]$, of size $S$, over $\mathbb{F}(\epsilon)$, and a polynomial $S(\boldsymbol{x}, \epsilon) \in \mathbb{F}[\epsilon][\boldsymbol{x}]$ such that $g(\boldsymbol{x}, \epsilon)=h(\boldsymbol{x})+\epsilon \cdot S(\boldsymbol{x}, \epsilon)$. In other words, $\lim _{\epsilon \rightarrow 0} g=h$.

- $\overline{\operatorname{size}}(h) \leq \operatorname{size}(h)$.

If $g$ has circuit of size $s$ over $\mathbb{F}(\epsilon)$, then one can assume that the highest degree of $\epsilon$ in $g$ can be exponentially large $2^{s^{2}}$ [Bürgisser 2004, 2020].

## Algebraic approximation (continued)

## Algebraic Approximation [Bürgisser 2004]

A polynomial $h(x) \in \mathbb{F}[\boldsymbol{x}]$ has approximative complexity $s$, if there is a circuit $g(\boldsymbol{x}, \epsilon) \in \mathbb{F}(\epsilon)[\boldsymbol{x}]$, of size $S$, over $\mathbb{F}(\epsilon)$, and a polynomial $S(\boldsymbol{x}, \epsilon) \in \mathbb{F}[\epsilon][\boldsymbol{x}]$ such that $g(\boldsymbol{x}, \epsilon)=h(\boldsymbol{x})+\epsilon \cdot S(\boldsymbol{x}, \epsilon)$. In other words, $\lim _{\epsilon \rightarrow 0} g=h$.

- $\overline{\operatorname{size}}(h) \leq \operatorname{size}(h)$.

If $g$ has circuit of size $s$ over $\mathbb{F}(\epsilon)$, then one can assume that the highest degree of $\epsilon$ in $g$ can be exponentially large $2^{s^{2}}$ [Bürgisser 2004, 2020].

Let us assume that $g(\boldsymbol{x}, \epsilon)=\sum_{i=0}^{M} g_{i} \cdot \epsilon^{i}$, where $M=2^{s^{2}}$. Note: $g_{0}=h$.

## Algebraic approximation (continued)

## Algebraic Approximation [Bürgisser 2004]

A polynomial $h(x) \in \mathbb{F}[\boldsymbol{x}]$ has approximative complexity $s$, if there is a circuit $g(\boldsymbol{x}, \epsilon) \in \mathbb{F}(\epsilon)[\boldsymbol{x}]$, of size $S$, over $\mathbb{F}(\epsilon)$, and a polynomial $S(\boldsymbol{x}, \epsilon) \in \mathbb{F}[\epsilon][\boldsymbol{x}]$ such that $g(\boldsymbol{x}, \epsilon)=h(\boldsymbol{x})+\epsilon \cdot S(\boldsymbol{x}, \epsilon)$. In other words, $\lim _{\epsilon \rightarrow 0} g=h$.

- $\overline{\operatorname{size}}(h) \leq \operatorname{size}(h)$.

If $g$ has circuit of size $s$ over $\mathbb{F}(\epsilon)$, then one can assume that the highest degree of $\epsilon$ in $g$ can be exponentially large $2^{s^{2}}$ [Bürgisser 2004, 2020].

Let us assume that $g(\boldsymbol{x}, \epsilon)=\sum_{i=0}^{M} g_{i} \cdot \epsilon^{i}$, where $M=2^{s^{2}}$. Note: $g_{0}=h$.
$>$ Pick $M+1$ many distinct values from $\mathbb{F}$ randomly and interpolate;

## Algebraic approximation (continued)

## Algebraic Approximation [Bürgisser 2004]

A polynomial $h(x) \in \mathbb{F}[\boldsymbol{x}]$ has approximative complexity $s$, if there is a circuit $g(\boldsymbol{x}, \epsilon) \in \mathbb{F}(\epsilon)[\boldsymbol{x}]$, of size $S$, over $\mathbb{F}(\epsilon)$, and a polynomial $S(\boldsymbol{x}, \epsilon) \in \mathbb{F}[\epsilon][\boldsymbol{x}]$ such that $g(\boldsymbol{x}, \epsilon)=h(\boldsymbol{x})+\epsilon \cdot S(\boldsymbol{x}, \epsilon)$. In other words, $\lim _{\epsilon \rightarrow 0} g=h$.

- $\overline{\operatorname{size}}(h) \leq \operatorname{size}(h)$.

If $g$ has circuit of size $s$ over $\mathbb{F}(\epsilon)$, then one can assume that the highest degree of $\epsilon$ in $g$ can be exponentially large $2^{s^{2}}$ [Bürgisser 2004, 2020].

Let us assume that $g(\boldsymbol{x}, \epsilon)=\sum_{i=0}^{M} g_{i} \cdot \epsilon^{i}$, where $M=2^{s^{2}}$. Note: $g_{0}=h$.
$>$ Pick $M+1$ many distinct values from $\mathbb{F}$ randomly and interpolate;
$>\operatorname{size}(h) \leq \exp (\overline{\operatorname{size}}(h))$.

## Algebraic approximation (continued)

## Algebraic Approximation [Bürgisser 2004]

A polynomial $h(x) \in \mathbb{F}[\boldsymbol{x}]$ has approximative complexity $s$, if there is a circuit $g(\boldsymbol{x}, \epsilon) \in \mathbb{F}(\epsilon)[\boldsymbol{x}]$, of size $S$, over $\mathbb{F}(\epsilon)$, and a polynomial $S(\boldsymbol{x}, \epsilon) \in \mathbb{F}[\epsilon][\boldsymbol{x}]$ such that $g(\boldsymbol{x}, \epsilon)=h(\boldsymbol{x})+\epsilon \cdot S(\boldsymbol{x}, \epsilon)$. In other words, $\lim _{\epsilon \rightarrow 0} g=h$.

- $\overline{\operatorname{size}}(h) \leq \operatorname{size}(h)$.

If $g$ has circuit of size $s$ over $\mathbb{F}(\epsilon)$, then one can assume that the highest degree of $\epsilon$ in $g$ can be exponentially large $2^{s^{2}}$ [Bürgisser 2004, 2020].

Let us assume that $g(\boldsymbol{x}, \epsilon)=\sum_{i=0}^{M} g_{i} \cdot \epsilon^{i}$, where $M=2^{s^{2}}$. Note: $g_{0}=h$.
$>$ Pick $M+1$ many distinct values from $\mathbb{F}$ randomly and interpolate;
$>\operatorname{size}(h) \leq \exp (\overline{\operatorname{size}}(h))$.
. $\overline{\operatorname{size}}(h) \leq \operatorname{size}(h) \leq \exp (\overline{\operatorname{size}}(h))$

## De-bordering

- De-bordering: Given a 'nice' class $\mathcal{C}$, can we de-border $\bar{C}$ ? i.e. find another 'nice' class $\mathcal{D}$ such that $\overline{\mathcal{C}} \subseteq \mathcal{D}$ ?


## De-bordering

De-bordering: Given a 'nice' class $C$, can we de-border $\bar{C}$ ? i.e. find another 'nice' class $\mathcal{D}$ such that $\bar{C} \subseteq \mathcal{D}$ ?

Take $C \in\{\mathrm{VBP}, \mathrm{VP}, \Sigma \wedge \Sigma, \mathrm{VNP}, \cdots\}$.

## De-bordering

De-bordering: Given a 'nice' class $C$, can we de-border $\bar{C}$ ? i.e. find another 'nice' class $\mathcal{D}$ such that $\bar{C} \subseteq \mathcal{D}$ ?

- Take $C \in\{\mathrm{VBP}, \mathrm{VP}, \Sigma \wedge \Sigma, \mathrm{VNP}, \cdots\}$.
[ Major open questions from [Mulmuley Sohoni 2001] and [Bürgisser 2001]:


## De-bordering

De-bordering: Given a 'nice' class $C$, can we de-border $\bar{C}$ ? i.e. find another 'nice' class $\mathcal{D}$ such that $\bar{C} \subseteq \mathcal{D}$ ?

Take $C \in\{\mathrm{VBP}, \mathrm{VP}, \Sigma \wedge \Sigma, \mathrm{VNP}, \cdots\}$.

Major open questions from [Mulmuley Sohoni 2001] and [Bürgisser 2001]:

$$
\overline{\mathrm{VBP}} \stackrel{?}{=} \mathrm{VBP}, \overline{\mathrm{VP}} \stackrel{?}{=} \mathrm{VP}, \overline{\mathrm{VNP}} \stackrel{?}{=} \mathrm{VNP} .
$$

## Strengthening lower bounds and its advantages

## Strengthening lower bounds and its advantages

## Strengthening Valiant's Conjecture [Milind Sohoni 2001]

VNP $\not \subset \overline{\mathrm{VBP}} \& \mathrm{VNP} \not \subset \overline{\mathrm{VP}}$. Equivalently, $\overline{\mathrm{dc}}\left(\right.$ perm $\left._{n}\right)$ and $\overline{\operatorname{size}}($ perm $n)$ are both $n^{\omega(1)}$.

## Strengthening lower bounds and its advantages

## Strengthening Valiant's Conjecture [Milind Sohoni 2001]

VNP $\not \subset \overline{\mathrm{VBP}} \& \mathrm{VNP} \not \subset \overline{\mathrm{VP}}$. Equivalently, $\overline{\mathrm{dc}}\left(\right.$ perm $\left._{n}\right)$ and $\overline{\operatorname{size}}\left(\right.$ perm $\left._{n}\right)$ are both $n^{\omega(1)}$.
$\square$ Both det and perm have 'nice' symmetries.

## Strengthening lower bounds and its advantages

## Strengthening Valiant's Conjecture [Milind Sohoni 2001]

VNP $\not \subset \overline{\mathrm{VBP}} \& \mathrm{VNP} \not \subset \overline{\mathrm{VP}}$. Equivalently, $\overline{\mathrm{dc}}\left(\right.$ perm $\left._{n}\right)$ and $\overline{\operatorname{size}}\left(\right.$ perm $\left._{n}\right)$ are both $n^{\omega(1)}$.
$\square$ Both det and perm have 'nice' symmetries.

- Symmetry-characterization avoids the Razborov-Rudich barrier: Very few functions are symmetry-characterized, so symmetry-characterization violates the largeness criterion!


## De-bordering results and their importance

## De-bordering results and their importance

A few known de-bordering results:

## De-bordering results and their importance

A few known de-bordering results:
$>\overline{\mathrm{VBP}_{\text {non-com }}}=\mathrm{VBP}_{\text {non-com }}$, in the noncommutative world [Nisan 1991].

## De-bordering results and their importance

A few known de-bordering results:
$>\overline{\mathrm{VBP}_{\text {non-com }}}=\mathrm{VBP}_{\text {non-com }}$, in the noncommutative world [Nisan 1991].
$>\overline{\Sigma \wedge \Sigma} \subsetneq$ VBP [Forbes 2016, Bläser-Dörfler-Ikenmeyer 2021].

## De-bordering results and their importance

A few known de-bordering results:
$>\overline{\mathrm{VBP}_{\text {non-com }}}=\mathrm{VBP}_{\text {non-com }}$, in the noncommutative world [Nisan 1991].
$>\overline{\Sigma \wedge \Sigma} \subsetneq$ VBP [Forbes 2016, Bläser-Dörfler-Ikenmeyer 2021].
$>\overline{\Sigma^{[s]} \Pi}=\Sigma^{[s]} \Pi$ and $\overline{\Pi^{[d]} \Sigma}=\Pi^{[d]} \Sigma$.

## De-bordering results and their importance

A few known de-bordering results:
$>\overline{\mathrm{VBP}_{\text {non-com }}}=\mathrm{VBP}_{\text {non-com }}$, in the noncommutative world [Nisan 1991].
$>\overline{\Sigma \wedge \Sigma} \subsetneq$ VBP [Forbes 2016, Bläser-Dörfler-Ikenmeyer 2021].
$>\overline{\Sigma^{[s]} \Pi}=\Sigma^{[s]} \Pi$ and $\overline{\Pi^{[d]} \Sigma}=\Pi^{[d]} \Sigma$.
U Upper bounds and lower bounds become more algebro-geometric in nature.

## De-bordering results and their importance

A few known de-bordering results:
$>\overline{\mathrm{VBP}_{\text {non-com }}}=\mathrm{VBP}_{\text {non-com }}$, in the noncommutative world [Nisan 1991].
$>\overline{\Sigma \wedge \Sigma} \subsetneq$ VBP [Forbes 2016, Bläser-Dörfler-Ikenmeyer 2021].
$>\overline{\Sigma^{[s]} \Pi}=\Sigma^{[s]} \Pi$ and $\overline{\Pi^{[d]} \Sigma}=\Pi^{[d]} \Sigma$.
Upper bounds and lower bounds become more algebro-geometric in nature.
Further potential applications in identity testing and understanding its 'robustness'.

## Border depth-3 circuits

## Depth-3 circuits

## Depth-3 circuits

- Depth-3 circuits with top fanin $k$, are denoted as $\Sigma^{[k]} \Pi^{[d]} \Sigma$. Thus, the size is trivially bounded by $O(k n d)$.


## Depth-3 circuits

Depth-3 circuits with top fanin $k$, are denoted as $\Sigma^{[k]} \Pi^{[d]} \Sigma$. Thus, the size is trivially bounded by $O(k n d)$.

They compute polynomials of the form $\sum_{i=1}^{k} \prod_{j=1}^{d} \ell_{i j}$, where $\ell_{i j}$ are linear polynomials (i.e. $a_{0}+a_{1} x_{1}+\ldots+a_{n} x_{n}$, for $a_{i} \in \mathbb{F}$ ).

## Depth-3 circuits

Depth-3 circuits with top fanin $k$, are denoted as $\Sigma^{[k]} \Pi^{[d]} \Sigma$. Thus, the size is trivially bounded by $O(k n d)$.

They compute polynomials of the form $\sum_{i=1}^{k} \prod_{j=1}^{d} \ell_{i j}$, where $\ell_{i j}$ are linear polynomials (i.e. $a_{0}+a_{1} x_{1}+\ldots+a_{n} x_{n}$, for $a_{i} \in \mathbb{F}$ ).
. How powerful are $\Sigma^{[k]} \Pi^{[d]} \Sigma$ circuits? Are they universal?

## Depth-3 circuits

Depth-3 circuits with top fanin $k$, are denoted as $\Sigma^{[k]} \Pi^{[d]} \Sigma$. Thus, the size is trivially bounded by $O(k n d)$.

They compute polynomials of the form $\sum_{i=1}^{k} \prod_{j=1}^{d} \ell_{i j}$, where $\ell_{i j}$ are linear polynomials (i.e. $a_{0}+a_{1} x_{1}+\ldots+a_{n} x_{n}$, for $a_{i} \in \mathbb{F}$ ).

- How powerful are $\Sigma^{[k]} \Pi^{[d]} \Sigma$ circuits? Are they universal?
- No.


## Depth-3 circuits

Depth-3 circuits with top fanin $k$, are denoted as $\Sigma^{[k]} \Pi^{[d]} \Sigma$. Thus, the size is trivially bounded by $O(k n d)$.

They compute polynomials of the form $\sum_{i=1}^{k} \prod_{j=1}^{d} \ell_{i j}$, where $\ell_{i j}$ are linear polynomials (i.e. $a_{0}+a_{1} x_{1}+\ldots+a_{n} x_{n}$, for $a_{i} \in \mathbb{F}$ ).

- How powerful are $\Sigma^{[k]} \Pi^{[d]} \Sigma$ circuits? Are they universal?
- No. E.g. the Inner Product polynomial $\langle\boldsymbol{x}, \boldsymbol{y}\rangle=x_{1} y_{1}+\ldots+x_{k+1} y_{k+1}$ cannot be written as a $\Sigma^{[k]} \Pi^{[d]} \Sigma$ circuit, regardless of the product fanin $d$ !


## Power of border depth-3 circuits

## Power of border depth-3 circuits

- What about $\overline{\Sigma^{[k]} \Pi^{[d]} \Sigma}$ circuits?


## Power of border depth-3 circuits

$\square$ What about $\overline{\Sigma^{[k]} \Pi^{[d]} \Sigma}$ circuits?
Recall: $h \in \overline{\Sigma^{[k]} \Pi^{[d]} \Sigma}$ of size $s$ if there exists a circuit $g$ such that

## Power of border depth-3 circuits

$\square$ What about $\overline{\Sigma^{[k]} \Pi^{[d]} \Sigma}$ circuits?
Recall: $h \in \overline{\Sigma^{[k]} \Pi^{[d]} \Sigma}$ of size $s$ if there exists a circuit $g$ such that

$$
g(\boldsymbol{x}, \epsilon)=h(\boldsymbol{x})+\epsilon \cdot S(\boldsymbol{x}, \epsilon),
$$

## Power of border depth-3 circuits

$\square$ What about $\overline{\Sigma^{[k]} \Pi^{[d]} \Sigma}$ circuits?
Recall: $h \in \overline{\Sigma^{[k]} \Pi^{[d]} \Sigma}$ of size $s$ if there exists a circuit $g$ such that

$$
g(\boldsymbol{x}, \epsilon)=h(\boldsymbol{x})+\epsilon \cdot S(\boldsymbol{x}, \epsilon),
$$

where $g$ can be computed by a $\Sigma^{[k]} \Pi^{[d]} \Sigma$ circuit, over $\mathbb{F}(\epsilon)$, of size $s$.

## Power of border depth-3 circuits

$\square$ What about $\overline{\Sigma^{[k]} \Pi^{[d]} \Sigma}$ circuits?
Recall: $h \in \overline{\Sigma^{[k]} \Pi^{[d]} \Sigma}$ of size $s$ if there exists a circuit $g$ such that

$$
g(\boldsymbol{x}, \epsilon)=h(\boldsymbol{x})+\epsilon \cdot S(\boldsymbol{x}, \epsilon),
$$

where $g$ can be computed by a $\Sigma^{[k]} \Pi^{[d]} \Sigma$ circuit, over $\mathbb{F}(\epsilon)$, of size $s$.

## Border depth-3 fanin 2 circuits are 'universal' [Kumar 2020]

Let $P$ be any homogeneous $n$-variate degree $d$ polynomial. Then, $P \in \overline{\Sigma^{[2]} \Pi^{[D]} \Sigma}$, where $D:=\exp (n, d)$.

## Proof of Kumar's result

## Proof.

1. Let $\mathrm{WR}(P)=: m$. Then, there are linear forms $\ell_{i}$ such that

## Proof of Kumar's result

## Proof.

1. Let $\mathrm{WR}(P)=: m$. Then, there are linear forms $\ell_{i}$ such that

$$
P=\sum_{i=1}^{m} \ell_{i}^{d} \quad[m \text { can be as large as } \exp (n, d)]
$$

## Proof of Kumar's result

## Proof.

1. Let $\mathrm{WR}(P)=: m$. Then, there are linear forms $\ell_{i}$ such that

$$
P=\sum_{i=1}^{m} \ell_{i}^{d} \quad[m \text { can be as large as } \exp (n, d)]
$$

2. Consider $\boldsymbol{A}(\boldsymbol{x}):=\prod_{i=1}^{m}\left(1+\ell_{i}^{d}\right)=\prod_{i=1}^{m} \prod_{j=1}^{d}\left(\alpha_{j}+\ell_{i}\right)$, for $\alpha_{j} \in \mathbb{C}$.

## Proof of Kumar's result

## Proof.

1. Let $\mathrm{WR}(P)=: m$. Then, there are linear forms $\ell_{i}$ such that

$$
P=\sum_{i=1}^{m} \ell_{i}^{d} \quad[m \text { can be as large as } \exp (n, d)]
$$

2. Consider $\boldsymbol{A}(\boldsymbol{x}):=\prod_{i=1}^{m}\left(1+\ell_{i}^{d}\right)=\prod_{i=1}^{m} \prod_{j=1}^{d}\left(\alpha_{j}+\ell_{i}\right)$, for $\alpha_{j} \in \mathbb{C}$. Note that

$$
A(\boldsymbol{x})=1+P+B \text { where } \operatorname{deg}(B) \geq 2 d
$$

## Proof of Kumar's result

## Proof.

1. Let $\mathrm{WR}(P)=: m$. Then, there are linear forms $\ell_{i}$ such that

$$
P=\sum_{i=1}^{m} \ell_{i}^{d} \quad[m \text { can be as large as } \exp (n, d)]
$$

2. Consider $\boldsymbol{A}(\boldsymbol{x}):=\prod_{i=1}^{m}\left(1+\ell_{i}^{d}\right)=\prod_{i=1}^{m} \prod_{j=1}^{d}\left(\alpha_{j}+\ell_{i}\right)$, for $\alpha_{j} \in \mathbb{C}$. Note that

$$
A(\boldsymbol{x})=1+P+B \text { where } \operatorname{deg}(B) \geq 2 d
$$

3. Replace $x_{i}$ by $\epsilon \cdot x_{i}$ to get that

## Proof of Kumar's result

## Proof.

1. Let $\mathrm{WR}(P)=: m$. Then, there are linear forms $\ell_{i}$ such that

$$
P=\sum_{i=1}^{m} \ell_{i}^{d} \quad[m \text { can be as large as } \exp (n, d)]
$$

2. Consider $\boldsymbol{A}(\boldsymbol{x}):=\prod_{i=1}^{m}\left(1+\ell_{i}^{d}\right)=\prod_{i=1}^{m} \prod_{j=1}^{d}\left(\alpha_{j}+\ell_{i}\right)$, for $\alpha_{j} \in \mathbb{C}$. Note that

$$
A(\boldsymbol{x})=1+P+B \text { where } \operatorname{deg}(B) \geq 2 d
$$

3. Replace $x_{i}$ by $\epsilon \cdot x_{i}$ to get that

$$
\prod_{i=1}^{m} \prod_{j=1}^{d}\left(\alpha_{j}+\epsilon \cdot \ell_{i}\right)=1+\epsilon^{d} \cdot P+\epsilon^{2 d} \cdot R(\boldsymbol{x}, \epsilon)
$$

## Proof of Kumar's result

## Proof.

1. Let $\mathrm{WR}(P)=: m$. Then, there are linear forms $\ell_{i}$ such that

$$
P=\sum_{i=1}^{m} \ell_{i}^{d} \quad[m \text { can be as large as } \exp (n, d)]
$$

2. Consider $\boldsymbol{A}(\boldsymbol{x}):=\prod_{i=1}^{m}\left(1+\ell_{i}^{d}\right)=\prod_{i=1}^{m} \prod_{j=1}^{d}\left(\alpha_{j}+\ell_{i}\right)$, for $\alpha_{j} \in \mathbb{C}$. Note that

$$
A(\boldsymbol{x})=1+P+B \text { where } \operatorname{deg}(B) \geq 2 d
$$

3. Replace $x_{i}$ by $\epsilon \cdot x_{i}$ to get that

$$
\prod_{i=1}^{m} \prod_{j=1}^{d}\left(\alpha_{j}+\epsilon \cdot \ell_{i}\right)=1+\epsilon^{d} \cdot P+\epsilon^{2 d} \cdot R(\boldsymbol{x}, \epsilon)
$$

4. Divide by $\epsilon^{d}$ and rearrange to get

$$
P+\epsilon^{d} \cdot R(\boldsymbol{x}, \epsilon)=-\epsilon^{-d}+\epsilon^{-d} \cdot \prod_{i=1}^{m} \prod_{j=1}^{d}\left(\alpha_{j}+\epsilon \cdot \ell_{i}\right) \in \Sigma^{[2]} \Pi^{[m d]} \Sigma .
$$

## De-bordering $\overline{\Sigma^{[2]} \Pi \Sigma}$ circuits

## De-bordering $\overline{\Sigma^{[2]} \Pi \Sigma}$ circuits

If $h$ is approximated by a $\Sigma^{[2]} \Pi^{[d]} \Sigma$ circuit with $d=$ poly $(n)$, what's the exact complexity of $h$ ?

## De-bordering $\overline{\Sigma^{[2]} \Pi \Sigma}$ circuits

If $h$ is approximated by a $\Sigma^{[2]} \Pi^{[d]} \Sigma$ circuit with $d=$ poly $(n)$, what's the exact complexity of $h$ ?
$>$ Is it even explicit?

## De-bordering $\overline{\Sigma^{[2]} \Pi \Sigma}$ circuits

- If $h$ is approximated by a $\Sigma^{[2]} \Pi^{[d]} \Sigma$ circuit with $d=\operatorname{poly}(n)$, what's the exact complexity of $h$ ?
$>$ Is it even explicit? If yes, $\overline{\Sigma^{[2]} \Pi^{[d]} \Sigma} \subseteq$ VNP?


## De-bordering $\overline{\Sigma^{[2]} \Pi \Sigma}$ circuits

If $h$ is approximated by a $\Sigma^{[2]} \Pi^{[d]} \Sigma$ circuit with $d=$ poly $(n)$, what's the exact complexity of $h$ ?
$>$ Is it even explicit? If yes, $\overline{\Sigma^{[2]} \Pi^{[d]} \Sigma} \subseteq$ VNP?

## Theorem 1 (Border of depth-3 top-fanin-2 circuit is 'easy')

[Dutta-Dwivedi-Saxena FOCS 2021].
$\overline{\Sigma^{[2]} \Pi^{[d]} \Sigma} \subseteq \mathrm{VBP}$, for $d=\operatorname{poly}(n)$.
In particular, any polynomial in the border of top-fanin- 2 size- $s$ depth- 3 circuits, can also be exactly computed by a linear projection of a poly $(s) \times \operatorname{poly}(s)$ determinant.

## De-bordering $\overline{\Sigma^{[2]} \Pi \Sigma}$ circuits

If $h$ is approximated by a $\Sigma^{[2]} \Pi^{[d]} \Sigma$ circuit with $d=$ poly $(n)$, what's the exact complexity of $h$ ?
$>$ Is it even explicit? If yes, $\overline{\Sigma^{[2]} \Pi^{[d]} \Sigma} \subseteq$ VNP?

Theorem 1 (Border of depth-3 top-fanin-2 circuit is 'easy')
[Dutta-Dwivedi-Saxena FOCS 2021].
$\overline{\Sigma^{[2]} \Pi^{[d]} \Sigma} \subseteq \mathrm{VBP}$, for $d=\operatorname{poly}(n)$.
In particular, any polynomial in the border of top-fanin-2 size-s depth-3 circuits, can also be exactly computed by a linear projection of a poly $(s) \times$ poly $(s)$ determinant.

Remark. The result holds if one replaces the top-fanin-2 by arbitrary constant $k$.

## Why $k=2$ is hard to analyze?

## Why $k=2$ is hard to analyze?

Deep cancellations for $k=2$ make things harder.

## Why $k=2$ is hard to analyze?

Deep cancellations for $k=2$ make things harder.
$\square$ E.g., $T_{1}:=\epsilon^{-3}\left(1+\epsilon x_{1}+\epsilon^{2} x_{2}+\epsilon^{3} x_{3}+\ldots\right)$,

## Why $k=2$ is hard to analyze?

Deep cancellations for $k=2$ make things harder.
E.g., $T_{1}:=\epsilon^{-3}\left(1+\epsilon x_{1}+\epsilon^{2} x_{2}+\epsilon^{3} x_{3}+\ldots\right), T_{2}:=\epsilon^{-3}\left(1+\epsilon x_{1}+\epsilon^{2} x_{2}+\epsilon^{3} x_{4}+\ldots\right)$.

## Why $k=2$ is hard to analyze?

Deep cancellations for $k=2$ make things harder.
E.g., $T_{1}:=\epsilon^{-3}\left(1+\epsilon x_{1}+\epsilon^{2} x_{2}+\epsilon^{3} x_{3}+\ldots\right), T_{2}:=\epsilon^{-3}\left(1+\epsilon x_{1}+\epsilon^{2} x_{2}+\epsilon^{3} x_{4}+\ldots\right)$. Note, $\lim _{\epsilon \rightarrow 0}\left(T_{1}-T_{2}\right)=\left(x_{3}-x_{4}\right)$.

## Why $k=2$ is hard to analyze?

Deep cancellations for $k=2$ make things harder.
E. E.g., $T_{1}:=\epsilon^{-3}\left(1+\epsilon x_{1}+\epsilon^{2} x_{2}+\epsilon^{3} x_{3}+\ldots\right), T_{2}:=\epsilon^{-3}\left(1+\epsilon x_{1}+\epsilon^{2} x_{2}+\epsilon^{3} x_{4}+\ldots\right)$. Note, $\lim _{\epsilon \rightarrow 0}\left(T_{1}-T_{2}\right)=\left(x_{3}-x_{4}\right)$.

- Note $x^{2} \equiv\left(x-\epsilon^{M / 2} \cdot a\right)\left(x+\epsilon^{M / 2} \cdot a\right) \bmod \epsilon^{M}$, for any $a \in \mathbb{F}$.


## Why $k=2$ is hard to analyze?

Deep cancellations for $k=2$ make things harder.
E.g., $T_{1}:=\epsilon^{-3}\left(1+\epsilon x_{1}+\epsilon^{2} x_{2}+\epsilon^{3} x_{3}+\ldots\right), T_{2}:=\epsilon^{-3}\left(1+\epsilon x_{1}+\epsilon^{2} x_{2}+\epsilon^{3} x_{4}+\ldots\right)$. Note, $\lim _{\epsilon \rightarrow 0}\left(T_{1}-T_{2}\right)=\left(x_{3}-x_{4}\right)$.

- Note $x^{2} \equiv\left(x-\epsilon^{M / 2} \cdot a\right)\left(x+\epsilon^{M / 2} \cdot a\right) \bmod \epsilon^{M}$, for any $a \in \mathbb{F}$.
- Moreover,

$$
\lim _{\epsilon \rightarrow 0} \frac{1}{\epsilon^{M}} \cdot\left(x^{2}-\left(x-\epsilon^{M / 2} \cdot a\right)\left(x+\epsilon^{M / 2} \cdot a\right)\right)=a^{2}
$$

## Why $k=2$ is hard to analyze?

Deep cancellations for $k=2$ make things harder.
E. E.g., $T_{1}:=\epsilon^{-3}\left(1+\epsilon x_{1}+\epsilon^{2} x_{2}+\epsilon^{3} x_{3}+\ldots\right), T_{2}:=\epsilon^{-3}\left(1+\epsilon x_{1}+\epsilon^{2} x_{2}+\epsilon^{3} x_{4}+\ldots\right)$. Note, $\lim _{\epsilon \rightarrow 0}\left(T_{1}-T_{2}\right)=\left(x_{3}-x_{4}\right)$.

- Note $x^{2} \equiv\left(x-\epsilon^{M / 2} \cdot a\right)\left(x+\epsilon^{M / 2} \cdot a\right) \bmod \epsilon^{M}$, for any $a \in \mathbb{F}$.
- Moreover,

$$
\lim _{\epsilon \rightarrow 0} \frac{1}{\epsilon^{M}} \cdot\left(x^{2}-\left(x-\epsilon^{M / 2} \cdot a\right)\left(x+\epsilon^{M / 2} \cdot a\right)\right)=a^{2}
$$

$\square$ Infinitely many factorizations may give infinitely many limits.

## Proof sketch for $k=2$

## Proof sketch for $k=2$

- $T_{1}+T_{2}=f(\boldsymbol{x})+\epsilon \cdot S(\boldsymbol{x}, \epsilon)$, where $T_{i} \in \Pi \Sigma$ in $\mathbb{F}(\epsilon)[\boldsymbol{x}]$. Assume $\operatorname{deg}(f)=: d$.


## Proof sketch for $k=2$

- $T_{1}+T_{2}=f(\boldsymbol{x})+\epsilon \cdot S(\boldsymbol{x}, \epsilon)$, where $T_{i} \in \Pi \Sigma$ in $\mathbb{F}(\epsilon)[\boldsymbol{x}]$. Assume $\operatorname{deg}(f)=: d$.

High-level idea: Reduce fanin 2 to 1 with a 'nice' form.

## Proof sketch for $k=2$

- $T_{1}+T_{2}=f(\boldsymbol{x})+\epsilon \cdot S(\boldsymbol{x}, \epsilon)$, where $T_{i} \in \Pi \Sigma$ in $\mathbb{F}(\epsilon)[\boldsymbol{x}]$. Assume $\operatorname{deg}(f)=: d$.

High-level idea: Reduce fanin 2 to 1 with a 'nice' form.
$\square$ Apply a map $\Phi$, defined by $\Phi: x_{i} \mapsto z \cdot x_{i}+\alpha_{i}$, where $\alpha_{i} \in \mathbb{F}$ are random.

## Proof sketch for $k=2$

$\square T_{1}+T_{2}=f(\boldsymbol{x})+\epsilon \cdot S(\boldsymbol{x}, \epsilon)$, where $T_{i} \in \Pi \Sigma$ in $\mathbb{F}(\epsilon)[\boldsymbol{x}]$. Assume $\operatorname{deg}(f)=: d$.
[ High-level idea: Reduce fanin 2 to 1 with a 'nice' form.
$\square$ Apply a map $\Phi$, defined by $\Phi: x_{i} \mapsto z \cdot x_{i}+\alpha_{i}$, where $\alpha_{i} \in \mathbb{F}$ are random.
$>$ The variable $z$ is the degree counter and enables derivation,

## Proof sketch for $k=2$

$\square T_{1}+T_{2}=f(\boldsymbol{x})+\epsilon \cdot S(\boldsymbol{x}, \epsilon)$, where $T_{i} \in \Pi \Sigma$ in $\mathbb{F}(\epsilon)[\boldsymbol{x}]$. Assume $\operatorname{deg}(f)=: d$.
High-level idea: Reduce fanin 2 to 1 with a 'nice' form.
$\square$ Apply a map $\Phi$, defined by $\Phi: x_{i} \mapsto z \cdot x_{i}+\alpha_{i}$, where $\alpha_{i} \in \mathbb{F}$ are random.
$>$ The variable $z$ is the degree counter and enables derivation,
$>\alpha_{i}$ to ensure: If $\ell \mid T_{i}$, then $\left.\Phi(\ell)\right|_{z=0}=\ell\left(\alpha_{1}, \ldots, \alpha_{n}\right) \in \mathbb{F}(\epsilon) \backslash\{0\}$.

## Proof sketch for $k=2$

$\square T_{1}+T_{2}=f(\boldsymbol{x})+\epsilon \cdot S(\boldsymbol{x}, \epsilon)$, where $T_{i} \in \Pi \Sigma$ in $\mathbb{F}(\epsilon)[\boldsymbol{x}]$. Assume $\operatorname{deg}(f)=: d$.
[ High-level idea: Reduce fanin 2 to 1 with a 'nice' form.
$\square$ Apply a map $\Phi$, defined by $\Phi: x_{i} \mapsto z \cdot x_{i}+\alpha_{i}$, where $\alpha_{i} \in \mathbb{F}$ are random.
$>$ The variable $z$ is the degree counter and enables derivation,
$>\alpha_{i}$ to ensure: If $\ell \mid T_{i}$, then $\left.\Phi(\ell)\right|_{z=0}=\ell\left(\alpha_{1}, \ldots, \alpha_{n}\right) \in \mathbb{F}(\epsilon) \backslash\{0\}$.
$\square$ It suffices to show that $\Phi(f)$ has small ABP.

## Proof sketch for $k=2$

$\square T_{1}+T_{2}=f(\boldsymbol{x})+\epsilon \cdot S(\boldsymbol{x}, \epsilon)$, where $T_{i} \in \Pi \Sigma$ in $\mathbb{F}(\epsilon)[\boldsymbol{x}]$. Assume $\operatorname{deg}(f)=: d$.
[ High-level idea: Reduce fanin 2 to 1 with a 'nice' form.
$\square$ Apply a map $\Phi$, defined by $\Phi: x_{i} \mapsto z \cdot x_{i}+\alpha_{i}$, where $\alpha_{i} \in \mathbb{F}$ are random.
$>$ The variable $z$ is the degree counter and enables derivation,
$>\alpha_{i}$ to ensure: If $\ell \mid T_{i}$, then $\left.\Phi(\ell)\right|_{z=0}=\ell\left(\alpha_{1}, \ldots, \alpha_{n}\right) \in \mathbb{F}(\epsilon) \backslash\{0\}$.
It suffices to show that $\Phi(f)$ has small ABP.
$\square$ We devise a technique called DiDIL Divide, Derive, Interpolate/ Induct with Limit.

## $k=2$ proof continued: Divide and Derive

## $k=2$ proof continued: Divide and Derive

$\square \operatorname{Let} \Phi\left(T_{i}\right)=: \epsilon^{a_{i}} \cdot \tilde{T}_{i}$, for $i \in[2]$, where $a_{i}:=\operatorname{val}_{\epsilon}\left(\Phi\left(T_{i}\right)\right)$.
val $\epsilon_{\epsilon}(\cdot)$ denotes the highest power of $\epsilon$ dividing it.

## $k=2$ proof continued: Divide and Derive

Let $\Phi\left(T_{i}\right)=: \epsilon^{a_{i}} \cdot \tilde{T}_{i}$, for $i \in[2]$, where $a_{i}:=\operatorname{val}_{\epsilon}\left(\Phi\left(T_{i}\right)\right)$.
$\square \operatorname{val}_{\epsilon}(\cdot)$ denotes the highest power of $\epsilon$ dividing it.
D Divide and Derive:

## $k=2$ proof continued: Divide and Derive

Let $\Phi\left(T_{i}\right)=: \epsilon^{a_{i}} \cdot \tilde{T}_{i}$, for $i \in[2]$, where $a_{i}:=\operatorname{val}_{\epsilon}\left(\Phi\left(T_{i}\right)\right)$.
$\square \operatorname{val}_{\epsilon}(\cdot)$ denotes the highest power of $\epsilon$ dividing it.
D Divide and Derive:

$$
\begin{align*}
f+\epsilon \cdot S & =T_{1}+T_{2} \\
\Longrightarrow \quad \Phi(f)+\epsilon \cdot \Phi(S) & =\Phi\left(T_{1}\right)+\Phi\left(T_{2}\right) \\
\Longrightarrow \quad \Phi(f) / \tilde{T}_{2}+\epsilon \cdot \Phi(S) / \tilde{T}_{2} & =\Phi\left(T_{1}\right) / \tilde{T}_{2}+\epsilon^{a_{2}} \\
\Longrightarrow \quad \partial_{z}\left(\Phi(f) / \tilde{T}_{2}\right)+\epsilon \cdot \partial_{z}\left(\Phi(S) / \tilde{T}_{2}\right) & =\partial_{z}\left(\Phi\left(T_{1}\right) / \tilde{T}_{2}\right)=: g_{1} . \tag{1}
\end{align*}
$$

## $k=2$ proof continued: Divide and Derive

Let $\Phi\left(T_{i}\right)=: \epsilon^{a_{i}} \cdot \tilde{T}_{i}$, for $i \in[2]$, where $a_{i}:=\operatorname{val}_{\epsilon}\left(\Phi\left(T_{i}\right)\right)$.
val $\epsilon(\cdot)$ denotes the highest power of $\epsilon$ dividing it.

- Divide and Derive:

$$
\begin{align*}
f+\epsilon \cdot S & =T_{1}+T_{2} \\
\Longrightarrow \quad \Phi(f)+\epsilon \cdot \Phi(S) & =\Phi\left(T_{1}\right)+\Phi\left(T_{2}\right) \\
\Longrightarrow \quad \Phi(f) / \tilde{T}_{2}+\epsilon \cdot \Phi(S) / \tilde{T}_{2} & =\Phi\left(T_{1}\right) / \tilde{T}_{2}+\epsilon^{a_{2}} \\
\Longrightarrow \quad \partial_{z}\left(\Phi(f) / \tilde{T}_{2}\right)+\epsilon \cdot \partial_{z}\left(\Phi(S) / \tilde{T}_{2}\right) & =\partial_{z}\left(\Phi\left(T_{1}\right) / \tilde{T}_{2}\right)=: g_{1} . \tag{1}
\end{align*}
$$

- $\lim _{\epsilon \rightarrow 0} g_{1}=\partial_{Z}\left(\Phi(f) / t_{2}\right)$, where $t_{2}:=\lim _{\epsilon \rightarrow 0} \tilde{T_{2}}$.


## $k=2$ proof continued

## $k=2$ proof continued

- First target: compute $\lim _{\epsilon \rightarrow 0} g_{1}=\partial_{z}\left(\Phi(f) / t_{2}\right)$.


## $k=2$ proof continued

$\square$ First target: compute $\lim _{\epsilon \rightarrow 0} g_{1}=\partial_{Z}\left(\Phi(f) / t_{2}\right)$.
$\square$ Logarithmic derivative: $\operatorname{dlog}_{z}(h):=\partial_{z}(h) / h$.

## $k=2$ proof continued

- First target: compute $\lim _{\epsilon \rightarrow 0} g_{1}=\partial_{z}\left(\Phi(f) / t_{2}\right)$.

Logarithmic derivative: $\operatorname{dlog}_{z}(h):=\partial_{z}(h) / h$.
$\square$ dlog linearizes product: $\operatorname{dlog}\left(h_{1} h_{2}\right)=\operatorname{dlog}\left(h_{1}\right)+\operatorname{dlog}\left(h_{2}\right)$.

## $k=2$ proof continued

- First target: compute $\lim _{\epsilon \rightarrow 0} g_{1}=\partial_{z}\left(\Phi(f) / t_{2}\right)$.

Logarithmic derivative: $\operatorname{dlog}_{z}(h):=\partial_{z}(h) / h$.
$\square$ dlog linearizes product: $\operatorname{dlog}\left(h_{1} h_{2}\right)=\operatorname{dlog}\left(h_{1}\right)+\operatorname{dlog}\left(h_{2}\right)$. Note:

$$
\begin{aligned}
\partial_{z}\left(\Phi\left(T_{1}\right) / \tilde{T}_{2}\right) & =\Phi\left(T_{1}\right) / \tilde{T}_{2} \cdot \operatorname{dlog}\left(\Phi\left(T_{1}\right) / \tilde{T}_{2}\right) \\
& =(\Pi \Sigma / \Pi \Sigma) \cdot \operatorname{dlog}(\Pi \Sigma / \Pi \Sigma) \\
& =\Pi \Sigma / \Pi \Sigma \cdot\left( \pm \sum \operatorname{dlog}(\Sigma)\right)
\end{aligned}
$$

## $k=2$ proof continued

- First target: compute $\lim _{\epsilon \rightarrow 0} g_{1}=\partial_{z}\left(\Phi(f) / t_{2}\right)$.

Logarithmic derivative: $\operatorname{dlog}_{z}(h):=\partial_{z}(h) / h$.
$\square$ dlog linearizes product: $\operatorname{dlog}\left(h_{1} h_{2}\right)=\operatorname{dlog}\left(h_{1}\right)+\operatorname{dlog}\left(h_{2}\right)$. Note:

$$
\begin{aligned}
\partial_{z}\left(\Phi\left(T_{1}\right) / \tilde{T}_{2}\right) & =\Phi\left(T_{1}\right) / \tilde{T}_{2} \cdot \operatorname{dlog}\left(\Phi\left(T_{1}\right) / \tilde{T}_{2}\right) \\
& =(\Pi \Sigma / \Pi \Sigma) \cdot \operatorname{dlog}(\Pi \Sigma / \Pi \Sigma) \\
& =\Pi \Sigma / \Pi \Sigma \cdot\left( \pm \sum \operatorname{dlog}(\Sigma)\right)
\end{aligned}
$$

$\square$ Here $\Sigma$ means just a linear polynomial $\ell$.

## $k=2$ proof continued: Quick recap

## $k=2$ proof continued: Quick recap

$\square$ Recap: $\partial_{Z}\left(\Phi(f) / t_{2}\right)=\lim _{\epsilon \rightarrow 0} g_{1}=\lim _{\epsilon \rightarrow 0}(\Pi \Sigma / \Pi \Sigma) \cdot\left( \pm \sum \operatorname{dlog}(\Sigma)\right)$.

## $k=2$ proof continued: Quick recap

$\square$ Recap: $\partial_{Z}\left(\Phi(f) / t_{2}\right)=\lim _{\epsilon \rightarrow 0} g_{1}=\lim _{\epsilon \rightarrow 0}(\Pi \Sigma / \Pi \Sigma) \cdot\left( \pm \sum \operatorname{dlog}(\Sigma)\right)$.
$\square \operatorname{deg}(f)=d \Longrightarrow \operatorname{deg}_{z}(\Phi(f))=d \Longrightarrow \operatorname{deg}_{z}\left(\partial_{z}(\Phi(f))\right)=d-1$.

## $k=2$ proof continued: Quick recap

$\square$ Recap: $\partial_{Z}\left(\Phi(f) / t_{2}\right)=\lim _{\epsilon \rightarrow 0} g_{1}=\lim _{\epsilon \rightarrow 0}(\Pi \Sigma / \Pi \Sigma) \cdot\left( \pm \sum \mathrm{dlog}(\Sigma)\right)$.
$\square \operatorname{deg}(f)=d \Longrightarrow \operatorname{deg}_{z}(\Phi(f))=d \Longrightarrow \operatorname{deg}_{z}\left(\partial_{z}(\Phi(f))\right)=d-1$.

- Suffices to compute $\lim _{\epsilon \rightarrow 0} g_{1} \bmod z^{d}$.


## $k=2$ proof: dlog strikes!

- What is $\mathrm{dlog}(\ell)$ for a linear polynomial $\ell=A-z \cdot B$ ?


## $k=2$ proof: dlog strikes!

What is $\operatorname{dlog}(\ell)$ for a linear polynomial $\ell=A-z \cdot B$ ?

$$
\begin{aligned}
\operatorname{dlog}(A-z B) & =\frac{-B}{A(1-z \cdot B / A)} \\
& =-\frac{B}{A} \cdot \sum_{j=0}^{d-1}\left(\frac{z \cdot B}{A}\right)^{j} \bmod z^{d} \\
& \in \Sigma \wedge \Sigma
\end{aligned}
$$

## $k=2$ proof: dlog strikes!

What is $\operatorname{dlog}(\ell)$ for a linear polynomial $\ell=A-z \cdot B$ ?

$$
\begin{aligned}
\operatorname{dlog}(A-z B) & =\frac{-B}{A(1-z \cdot B / A)} \\
& =-\frac{B}{A} \cdot \sum_{j=0}^{d-1}\left(\frac{z \cdot B}{A}\right)^{j} \bmod z^{d} \\
& \in \Sigma \wedge \Sigma
\end{aligned}
$$

Thus,

$$
\begin{aligned}
\lim _{\epsilon \rightarrow 0} g_{1} \bmod z^{d} & \equiv \lim _{\epsilon \rightarrow 0} \Pi \Sigma / \Pi \Sigma \cdot\left(\sum \mathrm{dlog}(\Sigma)\right) \bmod z^{d} \\
& \equiv \lim _{\epsilon \rightarrow 0}(\Pi \Sigma / \Pi \Sigma) \cdot(\Sigma \wedge \Sigma) \bmod z^{d} \\
& \in \overline{(\Pi \Sigma / \Pi \Sigma) \cdot(\Sigma \wedge \Sigma)} \bmod z^{d}
\end{aligned}
$$

## Finishing the proof

- $\overline{C \cdot \mathcal{D}} \subseteq \bar{C} \cdot \overline{\mathcal{D}}$. Therefore,


## Finishing the proof

- $\overline{C \cdot \mathcal{D}} \subseteq \bar{C} \cdot \bar{D}$. Therefore,

$$
\begin{aligned}
\overline{(\Pi \Sigma / \Pi \Sigma) \cdot(\Sigma \wedge \Sigma)} & \subseteq \overline{(\Pi \Sigma / \Pi \Sigma)} \cdot \overline{\Sigma \wedge \Sigma} \\
& \subseteq(\mathrm{ABP} / \mathrm{ABP}) \cdot \mathrm{ABP} \\
& =\mathrm{ABP} / \mathrm{ABP} .
\end{aligned}
$$

## Finishing the proof

- $\overline{C \cdot \mathcal{D}} \subseteq \bar{C} \cdot \bar{D}$. Therefore,

$$
\begin{aligned}
\overline{(\Pi \Sigma / \Pi \Sigma) \cdot(\Sigma \wedge \Sigma)} & \subseteq \overline{(\Pi \Sigma / \Pi \Sigma)} \cdot \overline{\Sigma \wedge \Sigma} \\
& \subseteq(\mathrm{ABP} / \mathrm{ABP}) \cdot \mathrm{ABP} \\
& =\mathrm{ABP} / \mathrm{ABP} .
\end{aligned}
$$

- Eliminate division to get: $\lim _{\epsilon \rightarrow 0} g_{1} \bmod z^{d} \equiv \mathrm{ABP} / \mathrm{ABP} \bmod z^{d}=\mathrm{ABP}$.


## Finishing the proof

- $\overline{C \cdot \mathcal{D}} \subseteq \bar{C} \cdot \bar{D}$. Therefore,

$$
\begin{aligned}
\overline{(\Pi \Sigma / \Pi \Sigma) \cdot(\Sigma \wedge \Sigma)} & \subseteq \overline{(\Pi \Sigma / \Pi \Sigma)} \cdot \overline{\Sigma \wedge \Sigma} \\
& \subseteq(\mathrm{ABP} / \mathrm{ABP}) \cdot \mathrm{ABP} \\
& =\mathrm{ABP} / \mathrm{ABP} .
\end{aligned}
$$

- Eliminate division to get: $\lim _{\epsilon \rightarrow 0} g_{1} \bmod z^{d} \equiv \mathrm{ABP} / \mathrm{ABP} \bmod z^{d}=\mathrm{ABP}$.
- Thus, $\partial_{z}\left(\Phi(f) / t_{2}\right)=\lim _{\epsilon \rightarrow 0} g_{1}=\operatorname{ABP}$.


## Finishing the proof

- $\overline{C \cdot \mathcal{D}} \subseteq \bar{C} \cdot \bar{D}$. Therefore,

$$
\begin{aligned}
\overline{(\Pi \Sigma / \Pi \Sigma) \cdot(\Sigma \wedge \Sigma)} & \subseteq \overline{(\Pi \Sigma / \Pi \Sigma)} \cdot \overline{\Sigma \wedge \Sigma} \\
& \subseteq(\mathrm{ABP} / \mathrm{ABP}) \cdot \mathrm{ABP} \\
& =\mathrm{ABP} / \mathrm{ABP} .
\end{aligned}
$$

- Eliminate division to get: $\lim _{\epsilon \rightarrow 0} g_{1} \bmod z^{d} \equiv \mathrm{ABP} / \mathrm{ABP} \bmod z^{d}=\mathrm{ABP}$.

Thus, $\partial_{z}\left(\Phi(f) / t_{2}\right)=\lim _{\epsilon \rightarrow 0} g_{1}=A B P$. Interpolate/ Induct with Limit:

## Finishing the proof

- $\overline{C \cdot \mathcal{D}} \subseteq \bar{C} \cdot \bar{D}$. Therefore,

$$
\begin{aligned}
\overline{(\Pi \Sigma / \Pi \Sigma) \cdot(\Sigma \wedge \Sigma)} & \subseteq \overline{(\Pi \Sigma / \Pi \Sigma)} \cdot \overline{\Sigma \wedge \Sigma} \\
& \subseteq(\mathrm{ABP} / \mathrm{ABP}) \cdot \mathrm{ABP} \\
& =\mathrm{ABP} / \mathrm{ABP} .
\end{aligned}
$$

- Eliminate division to get: $\lim _{\epsilon \rightarrow 0} g_{1} \bmod z^{d} \equiv \mathrm{ABP} / \mathrm{ABP} \bmod z^{d}=\mathrm{ABP}$.
- Thus, $\partial_{z}\left(\Phi(f) / t_{2}\right)=\lim _{\epsilon \rightarrow 0} g_{1}=A B P$. Interpolate/ Induct with Limit:

Thus, $\Phi(f) / t_{2}=\mathrm{ABP} \Longrightarrow \Phi(f)=\mathrm{ABP} \Longrightarrow f=\mathrm{ABP}$.

Derandomizing border depth-3 circuits

## Polynomial Identity Testing

## Polynomial Identity Testing

$\square$ Polynomial Identity Testing (PIT): Given a circuit $C$, test whether $C$ computes the zero polynomial (deterministically).

## Polynomial Identity Testing

$\square$ Polynomial Identity Testing (PIT): Given a circuit $C$, test whether $C$ computes the zero polynomial (deterministically).
> Blackbox-PIT asks for an algorithm to test the zeroness of a given algebraic circuit via mere query access.

## Polynomial Identity Testing

$\square$ Polynomial Identity Testing (PIT): Given a circuit $C$, test whether $C$ computes the zero polynomial (deterministically).
> Blackbox-PIT asks for an algorithm to test the zeroness of a given algebraic circuit via mere query access.

## Polynomial Identity Lemma [Ore, Demillo-Lipton, Schwartz, Zippel]

## Polynomial Identity Testing

$\square$ Polynomial Identity Testing (PIT): Given a circuit $C$, test whether $C$ computes the zero polynomial (deterministically).
> Blackbox-PIT asks for an algorithm to test the zeroness of a given algebraic circuit via mere query access.

## Polynomial Identity Lemma [Ore, Demillo-Lipton, Schwartz, Zippel]

If $P(\boldsymbol{x})$ is a nonzero polynomial of degree $d$, and $S \subseteq \mathbb{F}$ of size at least $d+1$, then $P(\mathbf{a}) \neq 0$ for some $\boldsymbol{a} \in S^{n}$.

## Polynomial Identity Testing

$\square$ Polynomial Identity Testing (PIT): Given a circuit $C$, test whether $C$ computes the zero polynomial (deterministically).
> Blackbox-PIT asks for an algorithm to test the zeroness of a given algebraic circuit via mere query access.

## Polynomial Identity Lemma [Ore, Demillo-Lipton, Schwartz, Zippel]

If $P(\boldsymbol{x})$ is a nonzero polynomial of degree $d$, and $S \subseteq \mathbb{F}$ of size at least $d+1$, then $P(\mathbf{a}) \neq 0$ for some $\boldsymbol{a} \in S^{n}$.

This above lemma puts PIT $\in$ RP.

## Polynomial Identity Testing

$\square$ Polynomial Identity Testing (PIT): Given a circuit $C$, test whether $C$ computes the zero polynomial (deterministically).
> Blackbox-PIT asks for an algorithm to test the zeroness of a given algebraic circuit via mere query access.

## Polynomial Identity Lemma [Ore, Demillo-Lipton, Schwartz, Zippel]

If $P(\boldsymbol{x})$ is a nonzero polynomial of degree $d$, and $S \subseteq \mathbb{F}$ of size at least $d+1$, then $P(\boldsymbol{a}) \neq 0$ for some $\boldsymbol{a} \in S^{n}$.

- This above lemma puts PIT $\in$ RP.
- Can we derandomize blackbox-PIT?


## Polynomial Identity Testing

$\square$ Polynomial Identity Testing (PIT): Given a circuit $C$, test whether $C$ computes the zero polynomial (deterministically).
> Blackbox-PIT asks for an algorithm to test the zeroness of a given algebraic circuit via mere query access.

## Polynomial Identity Lemma [Ore, Demillo-Lipton, Schwartz, Zippel]

If $P(\boldsymbol{x})$ is a nonzero polynomial of degree $d$, and $S \subseteq \mathbb{F}$ of size at least $d+1$, then $P(\boldsymbol{a}) \neq 0$ for some $\boldsymbol{a} \in S^{n}$.

- This above lemma puts PIT $\in$ RP.

Can we derandomize blackbox-PIT? Some special cases are derandomized.

## Polynomial Identity Testing

$\square$ Polynomial Identity Testing (PIT): Given a circuit $C$, test whether $C$ computes the zero polynomial (deterministically).
> Blackbox-PIT asks for an algorithm to test the zeroness of a given algebraic circuit via mere query access.

## Polynomial Identity Lemma [Ore, Demillo-Lipton, Schwartz, Zippel]

If $P(\boldsymbol{x})$ is a nonzero polynomial of degree $d$, and $S \subseteq \mathbb{F}$ of size at least $d+1$, then $P(\boldsymbol{a}) \neq 0$ for some $\boldsymbol{a} \in S^{n}$.

This above lemma puts PIT $\in$ RP.

- Can we derandomize blackbox-PIT? Some special cases are derandomized.

Derandomizing PIT, for restricted cases, has many algorithmic applications:

## Polynomial Identity Testing

$\square$ Polynomial Identity Testing (PIT): Given a circuit $C$, test whether $C$ computes the zero polynomial (deterministically).
$>$ Blackbox-PIT asks for an algorithm to test the zeroness of a given algebraic circuit via mere query access.

## Polynomial Identity Lemma [Ore, Demillo-Lipton, Schwartz, Zippel]

If $P(\boldsymbol{x})$ is a nonzero polynomial of degree $d$, and $S \subseteq \mathbb{F}$ of size at least $d+1$, then $P(\boldsymbol{a}) \neq 0$ for some $\boldsymbol{a} \in S^{n}$.

- This above lemma puts PIT $\in$ RP.

Can we derandomize blackbox-PIT? Some special cases are derandomized.
D Derandomizing PIT, for restricted cases, has many algorithmic applications:
$>$ Graph Theory [Lovasz'79], [Fenner-Gurjar-Theirauf' 19]

## Polynomial Identity Testing

$\square$ Polynomial Identity Testing (PIT): Given a circuit $C$, test whether $C$ computes the zero polynomial (deterministically).
> Blackbox-PIT asks for an algorithm to test the zeroness of a given algebraic circuit via mere query access.

## Polynomial Identity Lemma [Ore, Demillo-Lipton, Schwartz, Zippel]

If $P(\boldsymbol{x})$ is a nonzero polynomial of degree $d$, and $S \subseteq \mathbb{F}$ of size at least $d+1$, then $P(\boldsymbol{a}) \neq 0$ for some $\boldsymbol{a} \in S^{n}$.

This above lemma puts PIT $\in$ RP.
Can we derandomize blackbox-PIT? Some special cases are derandomized.
D Derandomizing PIT, for restricted cases, has many algorithmic applications:
$>$ Graph Theory [Lovasz' 79], [Fenner-Gurjar-Theirauf' 19]
$>$ Primality Testing [Agrawal-Kayal-Saxena'04].

## Border PIT

## Border hitting set

$\mathcal{H}$ is a hitting set for a class $\bar{C}$, if $g(x, \epsilon) \in \mathcal{C}_{\mathbb{F}(\epsilon)}$ approximates a non-zero polynomial $h(\boldsymbol{x})$, then $\exists \boldsymbol{a} \in \mathcal{H}$ such that $g(\boldsymbol{a}, \epsilon) \notin \epsilon \cdot \mathbb{F}[\epsilon]$, i.e. $h(\boldsymbol{a}) \neq 0$.

## Border PIT

## Border hitting set

$\mathcal{H}$ is a hitting set for a class $\bar{C}$, if $g(x, \epsilon) \in \mathcal{C}_{\mathbb{F}(\epsilon)}$ approximates a non-zero polynomial $h(\boldsymbol{x})$, then $\exists \boldsymbol{a} \in \mathcal{H}$ such that $g(\boldsymbol{a}, \epsilon) \notin \epsilon \cdot \mathbb{F}[\epsilon]$, i.e. $h(\boldsymbol{a}) \neq 0$.
$\square$ Finding $\boldsymbol{a} \in \mathbb{F}^{n}$ such that $g(\mathbf{a}, \epsilon) \neq 0$ does not suffice.

## Border PIT

## Border hitting set

$\mathcal{H}$ is a hitting set for a class $\bar{C}$, if $g(x, \epsilon) \in \mathcal{C}_{\mathbb{F}(\epsilon)}$ approximates a non-zero polynomial $h(\boldsymbol{x})$, then $\exists \boldsymbol{a} \in \mathcal{H}$ such that $g(\boldsymbol{a}, \epsilon) \notin \epsilon \cdot \mathbb{F}[\epsilon]$, i.e. $h(\boldsymbol{a}) \neq 0$.
$\square$ Finding $\boldsymbol{a} \in \mathbb{F}^{n}$ such that $g(\mathbf{a}, \epsilon) \neq 0$ does not suffice.
$\square h$ could have really high (exact) complexity compared to $g$.

## Border PIT

## Border hitting set

$\mathcal{H}$ is a hitting set for a class $\bar{C}$, if $g(x, \epsilon) \in C_{\mathbb{F}(\epsilon)}$ approximates a non-zero polynomial $h(\boldsymbol{x})$, then $\exists \boldsymbol{a} \in \mathcal{H}$ such that $g(\boldsymbol{a}, \epsilon) \notin \epsilon \cdot \mathbb{F}[\epsilon]$, i.e. $h(\boldsymbol{a}) \neq 0$.
$\square$ Finding $\boldsymbol{a} \in \mathbb{F}^{n}$ such that $g(\mathbf{a}, \epsilon) \neq 0$ does not suffice.
$\square h$ could have really high (exact) complexity compared to $g$.

- We know


## Border PIT

## Border hitting set

$\mathcal{H}$ is a hitting set for a class $\bar{C}$, if $g(x, \epsilon) \in C_{\mathbb{F}(\epsilon)}$ approximates a non-zero polynomial $h(\boldsymbol{x})$, then $\exists \boldsymbol{a} \in \mathcal{H}$ such that $g(\boldsymbol{a}, \epsilon) \notin \epsilon \cdot \mathbb{F}[\epsilon]$, i.e. $h(\boldsymbol{a}) \neq 0$.
$\square$ Finding $\boldsymbol{a} \in \mathbb{F}^{n}$ such that $g(\mathbf{a}, \epsilon) \neq 0$ does not suffice.
$\square h$ could have really high (exact) complexity compared to $g$.

- We know
$>$ polynomial-time hitting set for $\overline{\Pi \Sigma}=\Pi \Sigma$ [Klivans-Spielman 2001],


## Border PIT

## Border hitting set

$\mathcal{H}$ is a hitting set for a class $\bar{C}$, if $g(x, \epsilon) \in C_{\mathbb{F}(\epsilon)}$ approximates a non-zero polynomial $h(\boldsymbol{x})$, then $\exists \boldsymbol{a} \in \mathcal{H}$ such that $g(\boldsymbol{a}, \epsilon) \notin \epsilon \cdot \mathbb{F}[\epsilon]$, i.e. $h(\boldsymbol{a}) \neq 0$.
$\square$ Finding $\boldsymbol{a} \in \mathbb{F}^{n}$ such that $g(\mathbf{a}, \epsilon) \neq 0$ does not suffice.
$\square h$ could have really high (exact) complexity compared to $g$.

- We know
$>$ polynomial-time hitting set for $\overline{\Pi \Sigma}=\Pi \Sigma$ [Klivans-Spielman 2001],
$>$ quasipolynomial-time hitting set for $\overline{\Sigma \wedge \Sigma}$ [Forbes-Shpilka 2013].


## Border PIT

## Border hitting set

$\mathcal{H}$ is a hitting set for a class $\bar{C}$, if $g(x, \epsilon) \in C_{\mathbb{F}(\epsilon)}$ approximates a non-zero polynomial $h(\boldsymbol{x})$, then $\exists \boldsymbol{a} \in \mathcal{H}$ such that $g(\boldsymbol{a}, \epsilon) \notin \epsilon \cdot \mathbb{F}[\epsilon]$, i.e. $h(\boldsymbol{a}) \neq 0$.
$\square$ Finding $\boldsymbol{a} \in \mathbb{F}^{n}$ such that $g(\mathbf{a}, \epsilon) \neq 0$ does not suffice.
$\square h$ could have really high (exact) complexity compared to $g$.

- We know
$>$ polynomial-time hitting set for $\overline{\Pi \Sigma}=\Pi \Sigma$ [Klivans-Spielman 2001],
$>$ quasipolynomial-time hitting set for $\overline{\Sigma \wedge \Sigma}$ [Forbes-Shpilka 2013].
- $n^{O(k)}$-time hitting set is known for $\Sigma^{[k]} \Pi \Sigma$ [Saxena-Seshadri 2012].


## Border PIT

## Border hitting set

$\mathcal{H}$ is a hitting set for a class $\bar{C}$, if $g(x, \epsilon) \in C_{\mathbb{F}(\epsilon)}$ approximates a non-zero polynomial $h(\boldsymbol{x})$, then $\exists \boldsymbol{a} \in \mathcal{H}$ such that $g(\boldsymbol{a}, \epsilon) \notin \epsilon \cdot \mathbb{F}[\epsilon]$, i.e. $h(\boldsymbol{a}) \neq 0$.
$\square$ Finding $\mathbf{a} \in \mathbb{F}^{n}$ such that $g(\mathbf{a}, \epsilon) \neq 0$ does not suffice.
$\square h$ could have really high (exact) complexity compared to $g$.

- We know
$>$ polynomial-time hitting set for $\overline{\Pi \Sigma}=\Pi \Sigma$ [Klivans-Spielman 2001],
$>$ quasipolynomial-time hitting set for $\overline{\Sigma \wedge \Sigma}$ [Forbes-Shpilka 2013].
- $n^{O(k)}$-time hitting set is known for $\Sigma^{[k]} \Pi \Sigma$ [Saxena-Seshadri 2012]. Unfortunately, it does not work for $\overline{\Sigma^{[k]} \Pi \Sigma}$.


## Border PIT

## Border hitting set

$\mathcal{H}$ is a hitting set for a class $\bar{C}$, if $g(x, \epsilon) \in \mathcal{C}_{\mathbb{F}(\epsilon)}$ approximates a non-zero polynomial $h(\boldsymbol{x})$, then $\exists \boldsymbol{a} \in \mathcal{H}$ such that $g(\boldsymbol{a}, \epsilon) \notin \epsilon \cdot \mathbb{F}[\epsilon]$, i.e. $h(\boldsymbol{a}) \neq 0$.
$\square$ Finding $\boldsymbol{a} \in \mathbb{F}^{n}$ such that $g(\mathbf{a}, \epsilon) \neq 0$ does not suffice.
$\square h$ could have really high (exact) complexity compared to $g$.

- We know
$>$ polynomial-time hitting set for $\overline{\Pi \Sigma}=\Pi \Sigma$ [Klivans-Spielman 2001],
$>$ quasipolynomial-time hitting set for $\overline{\Sigma \wedge \Sigma}$ [Forbes-Shpilka 2013].
- $n^{O(k)}$-time hitting set is known for $\Sigma^{[k]} \Pi \Sigma$ [Saxena-Seshadri 2012]. Unfortunately, it does not work for $\overline{\Sigma^{[k]} \Pi \Sigma}$.
- General PIT for det is not known!


## Border PIT

## Border hitting set

$\mathcal{H}$ is a hitting set for a class $\bar{C}$, if $g(x, \epsilon) \in C_{\mathbb{F}(\epsilon)}$ approximates a non-zero polynomial $h(\boldsymbol{x})$, then $\exists \boldsymbol{a} \in \mathcal{H}$ such that $g(\boldsymbol{a}, \epsilon) \notin \epsilon \cdot \mathbb{F}[\epsilon]$, i.e. $h(\boldsymbol{a}) \neq 0$.
$\square$ Finding $\boldsymbol{a} \in \mathbb{F}^{n}$ such that $g(\mathbf{a}, \epsilon) \neq 0$ does not suffice.
$\square h$ could have really high (exact) complexity compared to $g$.

- We know
$>$ polynomial-time hitting set for $\overline{\Pi \Sigma}=\Pi \Sigma$ [Klivans-Spielman 2001],
$>$ quasipolynomial-time hitting set for $\overline{\Sigma \wedge \Sigma}$ [Forbes-Shpilka 2013].
- $n^{O(k)}$-time hitting set is known for $\Sigma^{[k]} \Pi \Sigma$ [Saxena-Seshadri 2012]. Unfortunately, it does not work for $\overline{\Sigma^{[k]} \Pi \Sigma}$.

General PIT for det is not known!

## Theorem 2 (Derandomizing polynomal-sized depth-3 top-fanin- $k$ circuits) [Dutta-Dwivedi-Saxena 2021]

There exists an explicit quasipolynomial-time $\left(s^{O(\log \log s)}\right)$ hitting set for size-s $\Sigma^{[k]} \Pi \Sigma$ circuits, for any constant $k$.

## Conclusion

## Concluding remarks

## Concluding remarks

$\square$ Can we show $\overline{\sum^{[k]} \Pi^{[d]} \Sigma} \neq \mathrm{VBP}$, for $d=\operatorname{poly}(n)$ ?

## Concluding remarks

$\square$ Can we show $\overline{\sum^{[k]} \Pi^{[d]} \Sigma} \neq \mathrm{VBP}$, for $d=\operatorname{poly}(n)$ ?

## Upcoming result by [Dutta-Saxena 2021, Preprint]

There is an explicit $n$-variate and $<n$ degree polynomial $f$ computed by size- $O(n)$ $\overline{\Sigma^{[k+1]} \Pi \Sigma}$ circuit, such that $f$ requires $2^{\Omega(n)}$-size $\overline{\Sigma^{[k]} \Pi \Sigma}$ circuits.

## Concluding remarks

$\square$ Can we show $\overline{\sum^{[k]} \Pi^{[d]} \Sigma} \neq \mathrm{VBP}$, for $d=\operatorname{poly}(n)$ ?

## Upcoming result by [Dutta-Saxena 2021, Preprint]

There is an explicit $n$-variate and $<n$ degree polynomial $f$ computed by size- $O(n)$ $\Sigma^{[k+1]} \Pi \Sigma$ circuit, such that $f$ requires $2^{\Omega(n)}$-size $\overline{\Sigma^{[k]} \Pi \Sigma}$ circuits.
$>$ This refined separation also establishes: $\overline{\Sigma^{[k]} \Pi^{[d]} \Sigma} \neq \mathrm{VBP}, \mathrm{VNP}$.

## Concluding remarks

$\square$ Can we show $\overline{\bar{\Sigma}^{[k]} \Pi^{[d]} \Sigma} \neq \mathrm{VBP}$, for $d=\operatorname{poly}(n)$ ?

## Upcoming result by [Dutta-Saxena 2021, Preprint]

There is an explicit $n$-variate and $<n$ degree polynomial $f$ computed by size- $O(n)$ $\Sigma^{[k+1]} \Pi \Sigma$ circuit, such that $f$ requires $2^{\Omega(n)}$-size $\Sigma^{[k]} \Pi \Sigma$ circuits.
$>$ This refined separation also establishes: $\overline{\Sigma^{[k]} \Pi^{[d]} \Sigma} \neq \mathrm{VBP}, \mathrm{VNP}$.
[Dutta-Dwivedi-Saxena 2021] showed a quasipolynomial-time hitting set for $\overline{\Sigma^{[k]} \Pi^{[d]} \Sigma}$ circuits. Can we improve it to polynomial?

## Concluding remarks

$\square$ Can we show $\overline{\bar{\Sigma}^{[k]} \Pi^{[d]} \Sigma} \neq \mathrm{VBP}$, for $d=\operatorname{poly}(n)$ ?

## Upcoming result by [Dutta-Saxena 2021, Preprint]

There is an explicit $n$-variate and $<n$ degree polynomial $f$ computed by size- $O(n)$ $\Sigma^{[k+1]} \Pi \Sigma$ circuit, such that $f$ requires $2^{\Omega(n)}$-size $\Sigma^{[k]} \Pi \Sigma$ circuits.
$>$ This refined separation also establishes: $\overline{\Sigma^{[k]} \Pi^{[d]} \Sigma} \neq \mathrm{VBP}, \mathrm{VNP}$.
[Dutta-Dwivedi-Saxena 2021] showed a quasipolynomial-time hitting set for $\overline{\Sigma^{[k]} \Pi^{[d]} \Sigma}$ circuits. Can we improve it to polynomial? In fact, it's poly-time for log-variate $\overline{\Sigma^{[k]} \Pi^{[d]} \Sigma}$ circuits.

## Concluding remarks

$\square$ Can we show $\overline{\bar{\Sigma}^{[k]} \Pi^{[d]} \Sigma} \neq \mathrm{VBP}$, for $d=\operatorname{poly}(n)$ ?

## Upcoming result by [Dutta-Saxena 2021, Preprint]

There is an explicit $n$-variate and $<n$ degree polynomial $f$ computed by size- $O(n)$ $\overline{\Sigma^{[k+1]} \Pi \Sigma}$ circuit, such that $f$ requires $2^{\Omega(n)}$-size $\overline{\Sigma^{[k]} \Pi \Sigma}$ circuits.
$>$ This refined separation also establishes: $\overline{\Sigma^{[k]} \Pi^{[d]} \Sigma} \neq \mathrm{VBP}, \mathrm{VNP}$.
[Dutta-Dwivedi-Saxena 2021] showed a quasipolynomial-time hitting set for $\Sigma^{[k]} \Pi^{[d]} \Sigma$ circuits. Can we improve it to polynomial? In fact, it's poly-time for log-variate $\overline{\Sigma^{[k]} \Pi^{[d]} \Sigma}$ circuits.

D Does our technique extend to arbitrary constant-depth border circuits? Currently it extends to restricted depth- 4 circuits.

## Concluding remarks

$\square$ Can we show $\overline{\bar{\Sigma}^{[k]} \Pi^{[d]} \Sigma} \neq \mathrm{VBP}$, for $d=\operatorname{poly}(n)$ ?

## Upcoming result by [Dutta-Saxena 2021, Preprint]

There is an explicit $n$-variate and $<n$ degree polynomial $f$ computed by size- $O(n)$ $\Sigma^{[k+1]} \Pi \Sigma$ circuit, such that $f$ requires $2^{\Omega(n)}$-size $\overline{\Sigma^{[k]} \Pi \Sigma}$ circuits.
$>$ This refined separation also establishes: $\overline{\Sigma^{[k]} \Pi^{[d]} \Sigma} \neq \mathrm{VBP}$, VNP.
[Dutta-Dwivedi-Saxena 2021] showed a quasipolynomial-time hitting set for $\overline{\Sigma^{[k]} \Pi^{[d]} \Sigma}$ circuits. Can we improve it to polynomial? In fact, it's poly-time for log-variate $\overline{\Sigma^{[k]} \Pi^{[d]} \Sigma}$ circuits.

Does our technique extend to arbitrary constant-depth border circuits? Currently it extends to restricted depth- 4 circuits.

Thank you.

## Concluding remarks

$\square$ Can we show $\overline{\bar{\Sigma}^{[k]} \Pi^{[d]} \Sigma} \neq \mathrm{VBP}$, for $d=\operatorname{poly}(n)$ ?

## Upcoming result by [Dutta-Saxena 2021, Preprint]

There is an explicit $n$-variate and $<n$ degree polynomial $f$ computed by size- $O(n)$ $\Sigma^{[k+1]} \Pi \Sigma$ circuit, such that $f$ requires $2^{\Omega(n)}$-size $\overline{\Sigma^{[k]} \Pi \Sigma}$ circuits.
$>$ This refined separation also establishes: $\overline{\Sigma^{[k]} \Pi^{[d]} \Sigma} \neq \mathrm{VBP}, \mathrm{VNP}$.
[Dutta-Dwivedi-Saxena 2021] showed a quasipolynomial-time hitting set for $\overline{\Sigma^{[k]} \Pi^{[d]} \Sigma}$ circuits. Can we improve it to polynomial? In fact, it's poly-time for log-variate $\overline{\Sigma^{[k]} \Pi^{[d]} \Sigma}$ circuits.

D Does our technique extend to arbitrary constant-depth border circuits? Currently it extends to restricted depth- 4 circuits.

Thank you. Questions?

